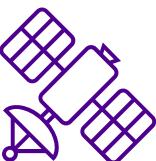


# Resilient PNT (positioning, navigation, and timing): emerging challenges and future directions

Prof. Heidi Kuusniemi, Tampere University  
SEDDIT annual workshop 2025, 19.11.2025, Linköping University



# Agenda

- What is PNT – and why does it matter?
- How GNSS works
- Vulnerabilities & threat models
- Real-world incidents
- Principles of resilient PNT
- Emerging mitigation & authentication
- Multi-layer PNT & LEO-PNT of the future
- Takeaways about the future of resilient PNT

# What is Positioning, Navigation and Timing (PNT)?

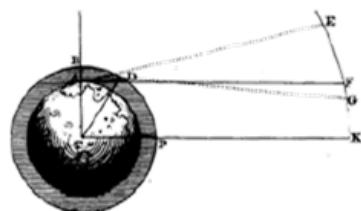
- PNT stands for Positioning, Navigation and Timing:
  - Positioning: the ability to determine location and orientation
  - Navigation: the ability to determine current and desired position
  - Timing: the ability to acquire and maintain accurate and precise time from a standard anywhere in the world
- PNT underpins many everyday activities in modern society including transport, telecommunications, computers, emergency services, personal navigation and finances
- Global Navigation Satellite Systems (GNSS) are the primary sources of PNT information worldwide

# The history of PNT

Celestial/Chrono

1770-1920

3000 m



Loran

1940s-2010

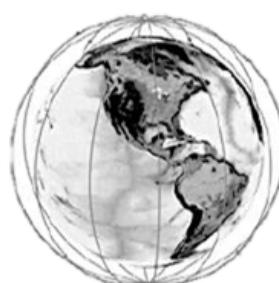
460 m



Transit

1964-1996

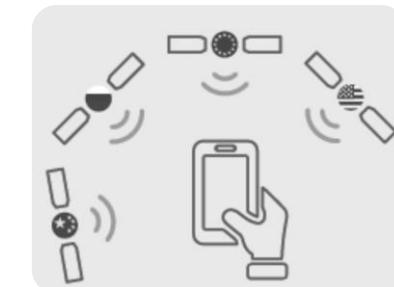
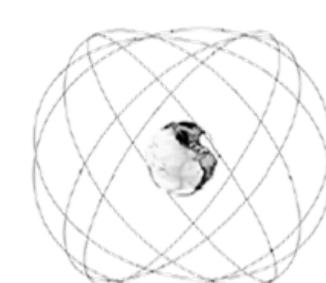
25 m



GNSS

1996-present

3 m - cm



# Why PNT matters

GNSS is for everyone - whether they know it or not

- Telecommunication networks rely on GNSS for time synchronization
- Banking transactions & stock exchanges → traceable global timing
- Power grids → phase synchronization
- Logistics & transportation → routing, AIS maritime, ADS-B aviation
- Everyday apps → Google Maps, Foodora, delivery routing etc

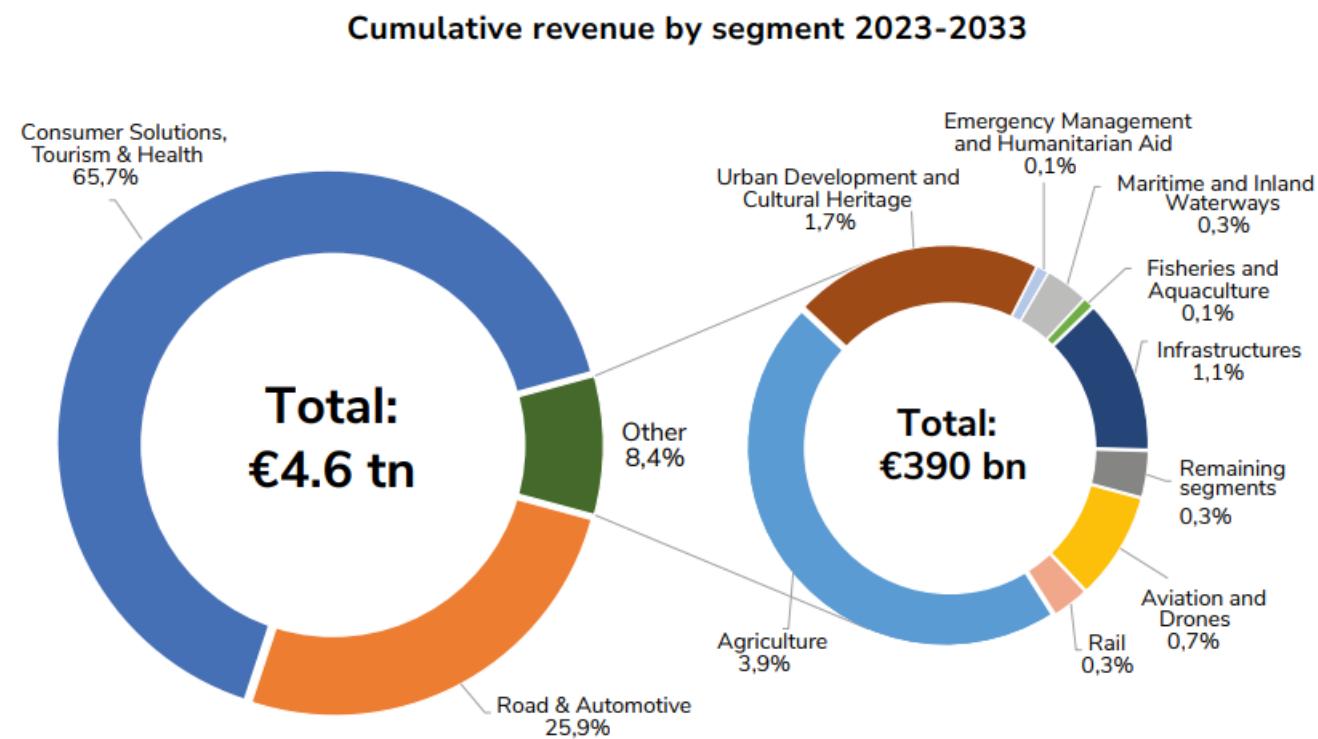
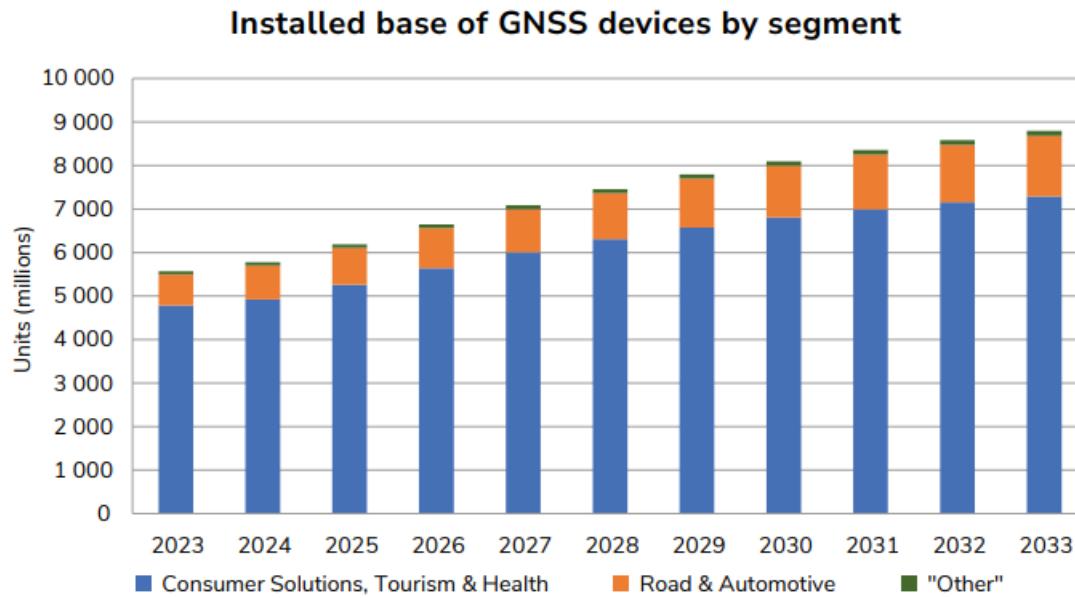


# PNT economically

Satellite navigation related revenue is ever increasing

*“Cumulative global GNSS downstream market revenues over the 2023 to 2033 period are expected to surpass €4.5 trillion”*

*“GNSS global revenues will rise from more than €260 billion in 2023 to around €580 billion in 2033”*



# How GNSS works (1)

- Multiple GNSS constellations exist (GPS, Galileo, GLONASS, BeiDou)
- Basic ranging principle: time-of-flight
- Satellites transmit open signals at very low power (~ -160 dBW at Earth's surface!)
  - by the time GNSS signals reach Earth, they are extremely faint, making them highly susceptible to RF interference
- GNSS receivers assume
  - signals are authentic
  - signals are unmodified
  - signals come from where they should in the sky

→ This is where cybersecurity intersects
- GNSS operates on trust: civilian GNSS signals have been unencrypted and unauthenticated, leaving them vulnerable to spoofing attacks

# How GNSS works (2)

Velocity x Time = Distance

Radio waves travel at the speed of light 299 792 458 m/s (i.e., around  $3 \times 10^8$  m/s)

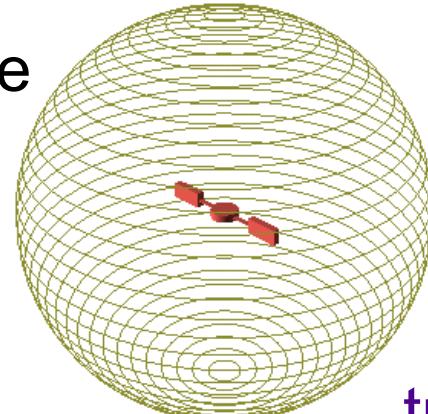
If it took, for example, 0.067 seconds to receive a signal transmitted by a satellite floating directly overhead, the travel distance of the received signal can be calculated using the above formula.

Travel distance:  $299792458 \text{ m/s} \times 0.067 \text{ s} = 20086094.69 \text{ m} \sim 20086 \text{ km}$

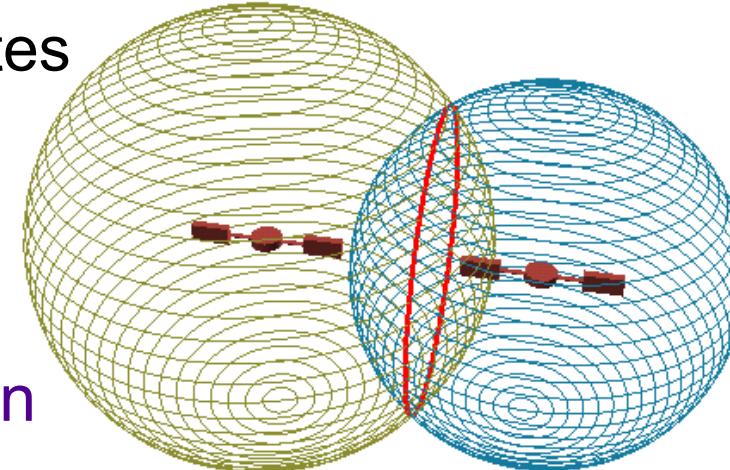
Precise **position of the satellite** at the time of signal transmission and travel **time** must be resolved!

# How GNSS works (3)

1 Satellite

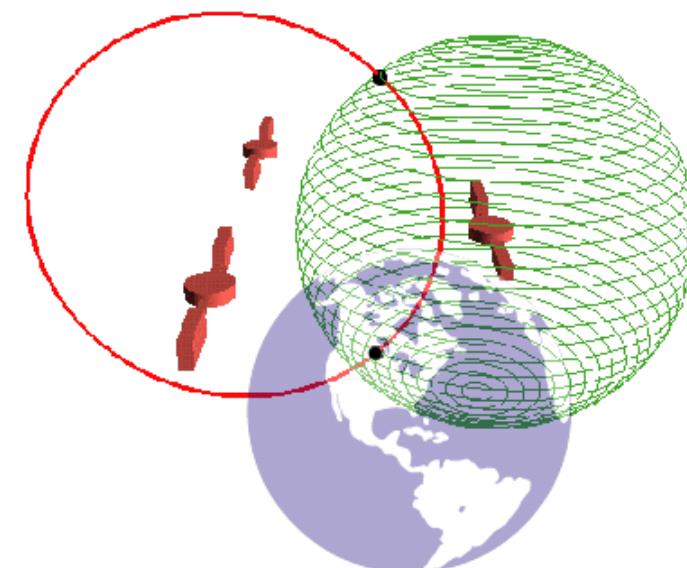
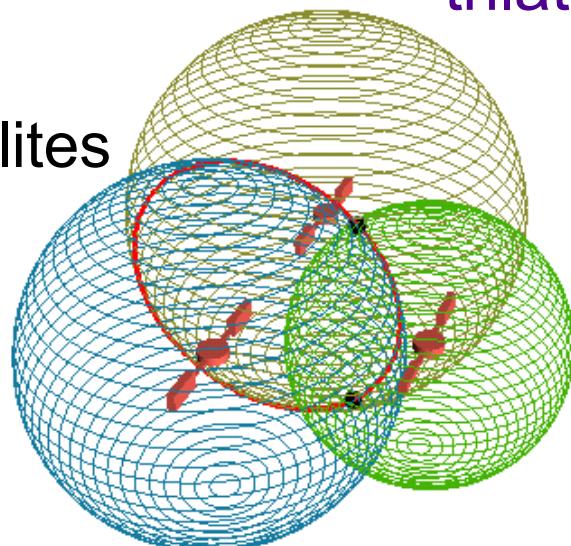


2 Satellites

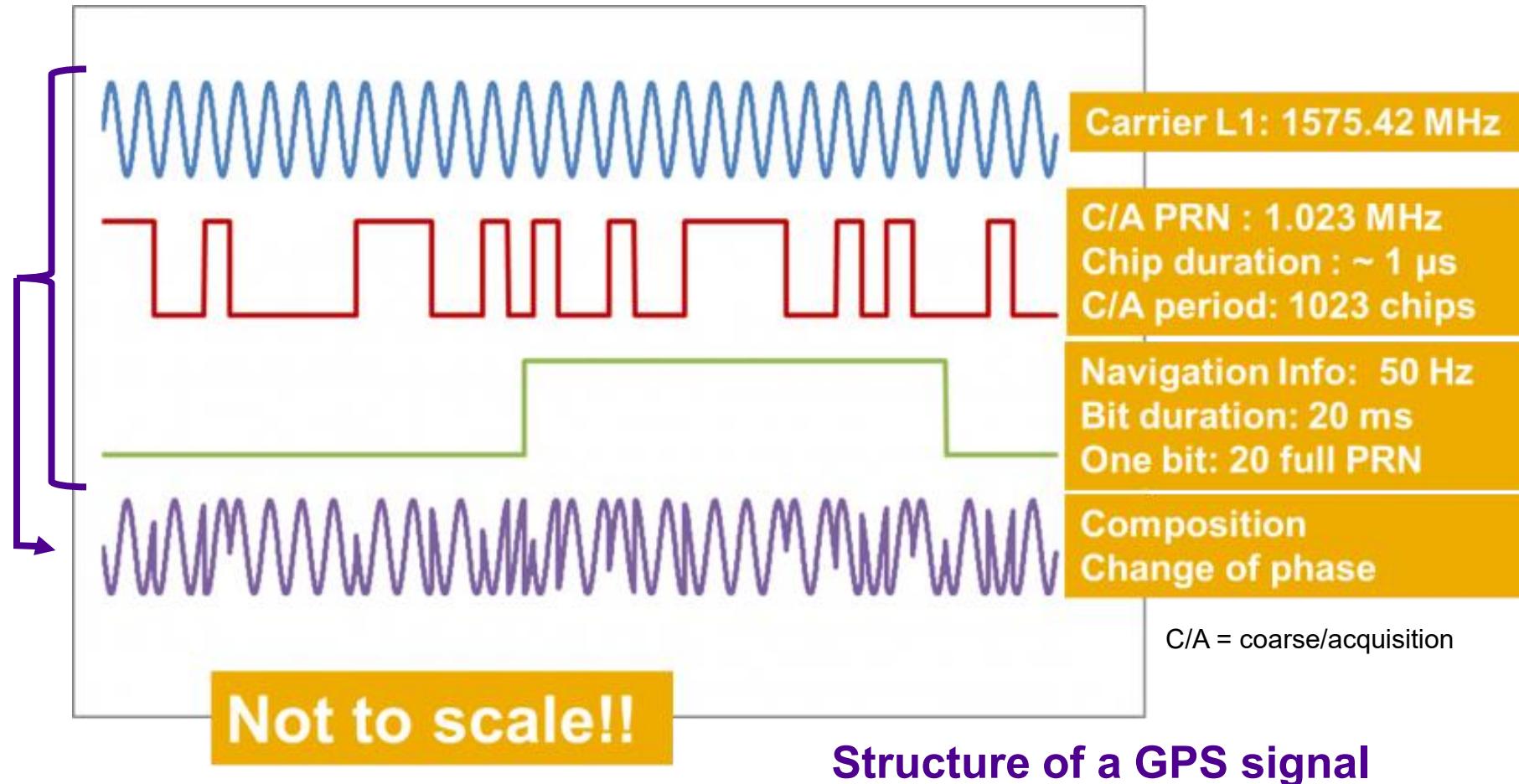


3D  
trilateration

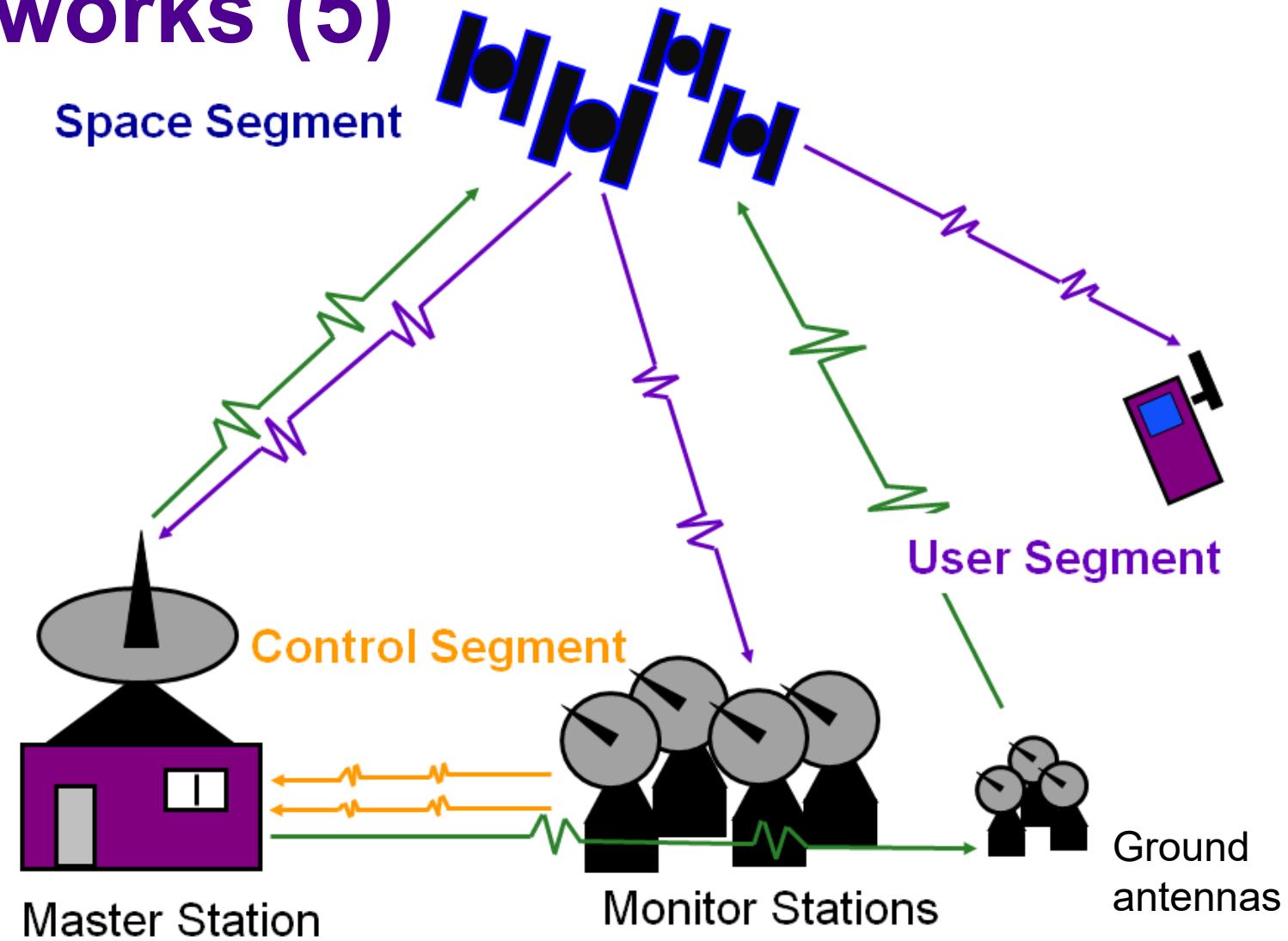
3 Satellites



# How GNSS works (4)



# How GNSS works (5)

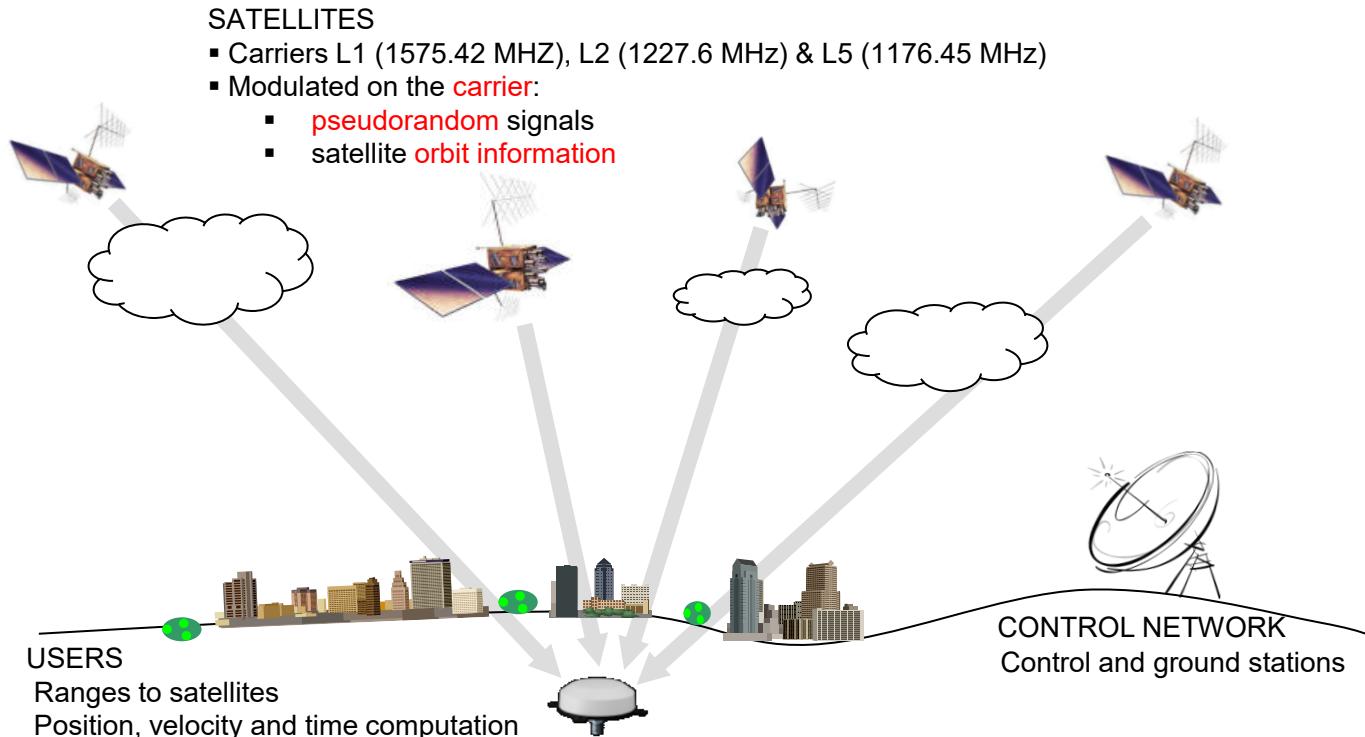


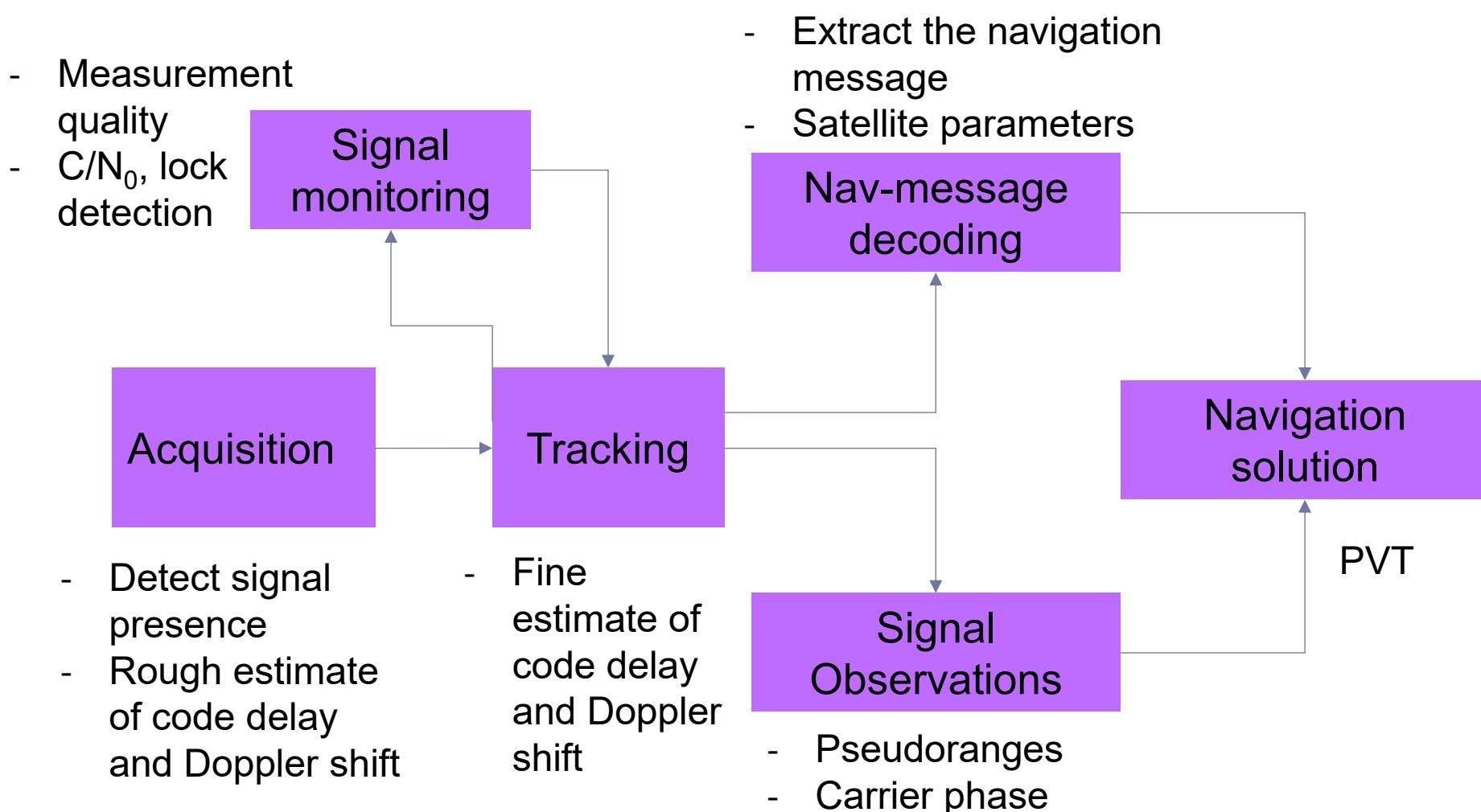
The three segments in a GNSS

# GPS as an GNSS example – basics

- Satellite navigation is based on radio signals transmitted by Earth-orbiting satellites and distance measurements between satellites and a user receiver
- A GPS receiver 1) measures the signal travel time from the satellite to the Earth, or 2) computes the number of full carrier cycles between a satellite and a receiver  
→ range measurements
- A receiver receives simultaneously information from multiple satellites through multiple channels
- When satellite locations are known, the user receiver location can be estimated based on the range measurements

GPS:

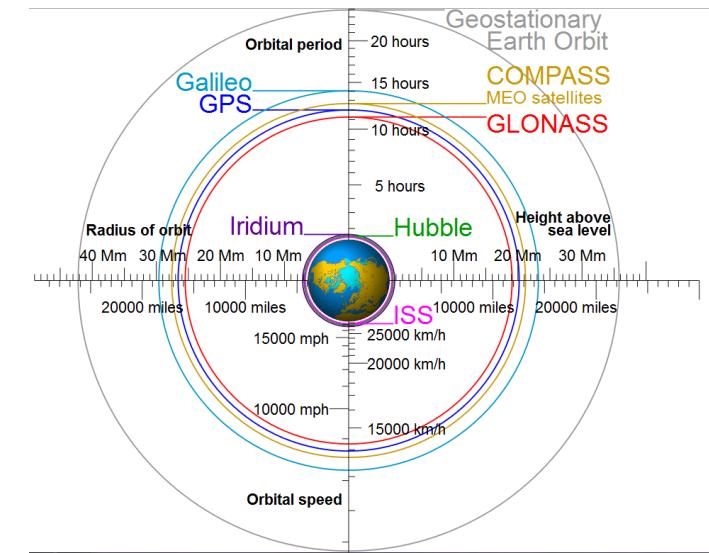




# GNSS signal processing stages in a receiver

# GNSS requirements

- GNSS needs a common time system
  - Each GNSS satellite has atomic clocks
  - User receivers have their own time
- The signal transmission time has to be measurable
  - Each GNSS satellite transmits a unique digital signature, which consists of an apparent random sequence
  - A time reference is transmitted using the *Navigation Message*
- Each signal source has to be distinguishable
  - GNSS utilizes code division multiple access (CDMA) or frequency division multiple access (FDMA)
- The position of each signal source must be known
  - Each satellite sends its orbit data using the *Navigation Message*
  - Orbit data: Almanac and Ephemeris



# GNSS accuracy

Accuracies obtainable:

10 m

Navigation; code measurement; one receiver

1 m

DGNSS; code measurement + base station

0.1 m

carrier phase observations + base station

0.01 m

Static positioning; phase observations, network of base stations, post processing

0.001 m

Permanent stations; time series

Issues affecting GNSS accuracy:

- *Receiver technology used*
- *Location and environment of the antenna*
- *Weather conditions*



# Multiple GNSSs

- The European **Galileo**, the Russian **Glonass**, and the Chinese **BeiDou** are similar systems with GPS
  - Glonass is however currently a FDMA system when GPS is and Galileo & BeiDou will be CDMA
    - Glonass has planned to be modernized to CDMA
  - Also **GPS** has been modernized: new civil and military signals on L2 and L5



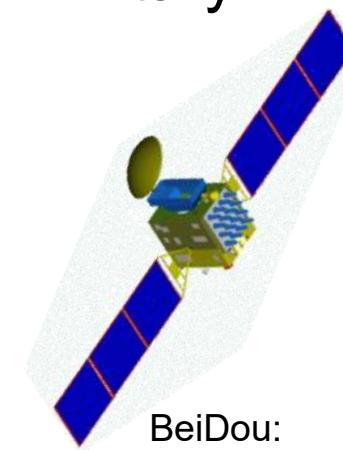
GPS  
~31 SV  
operational



Galileo  
~29 SV operational

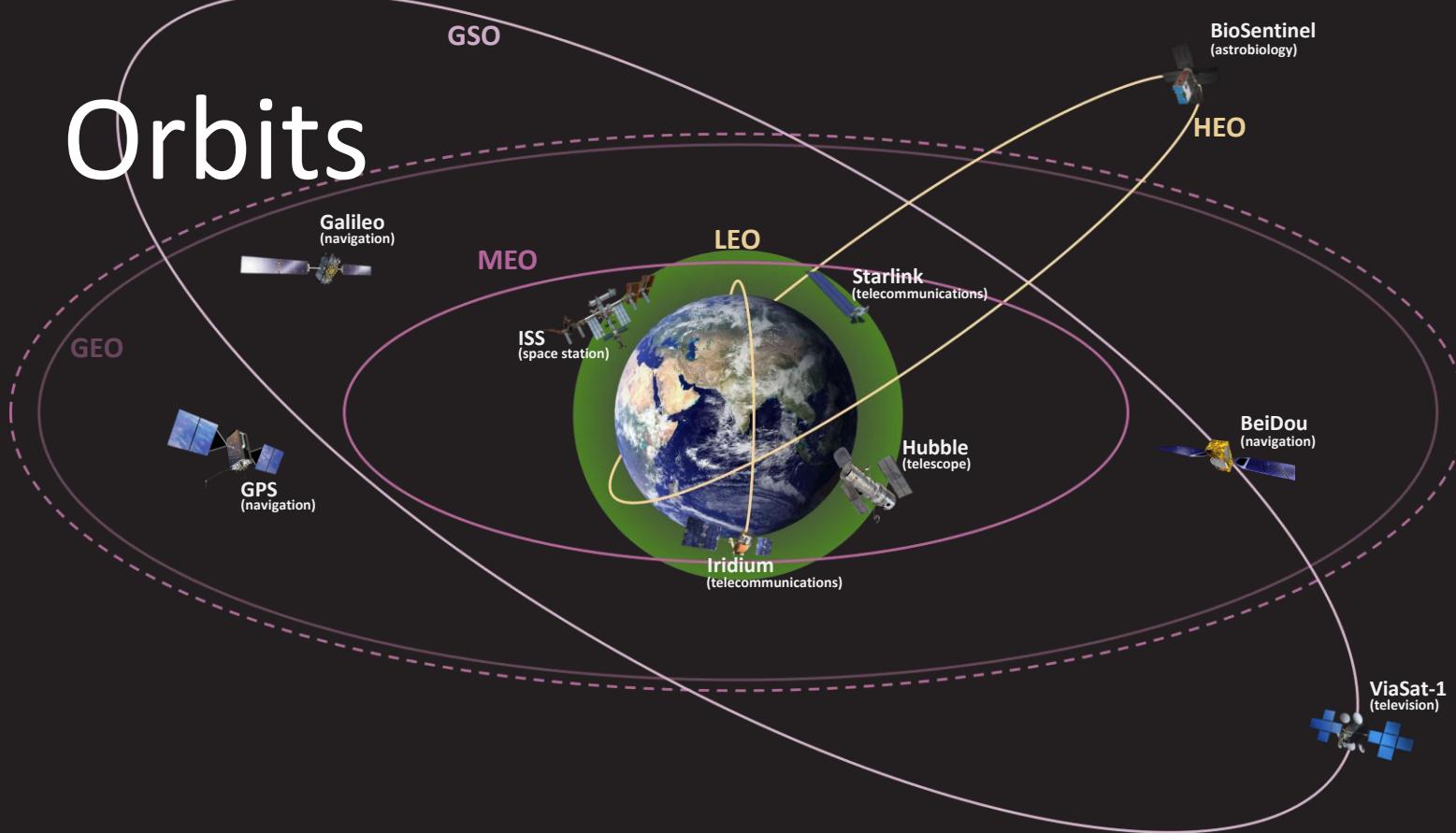


Glonass  
~24 SV  
operational

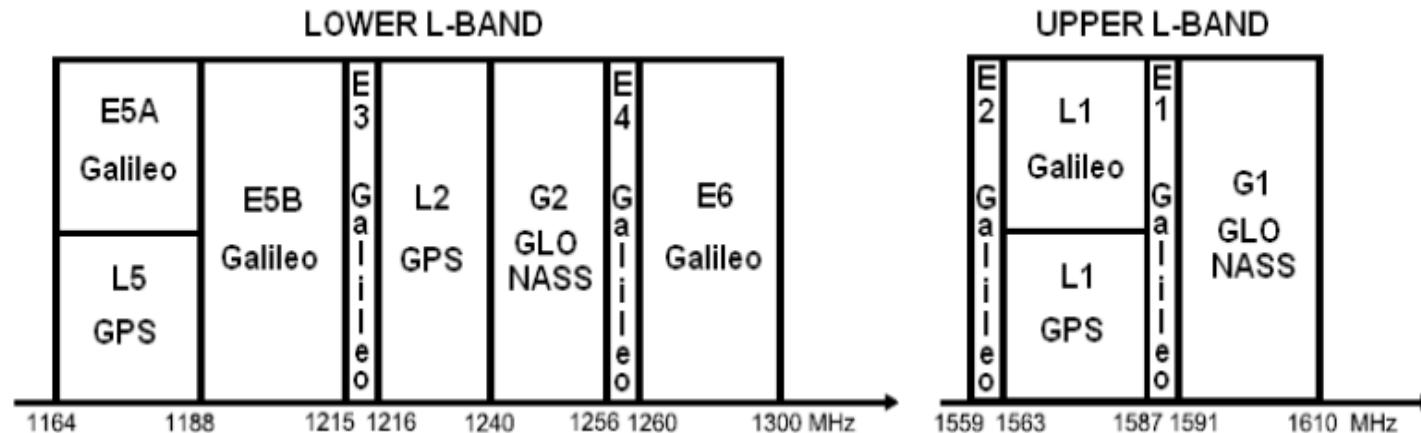


BeiDou:  
~44 SV  
operational

# Orbits



# GNSS frequency-wise (1)

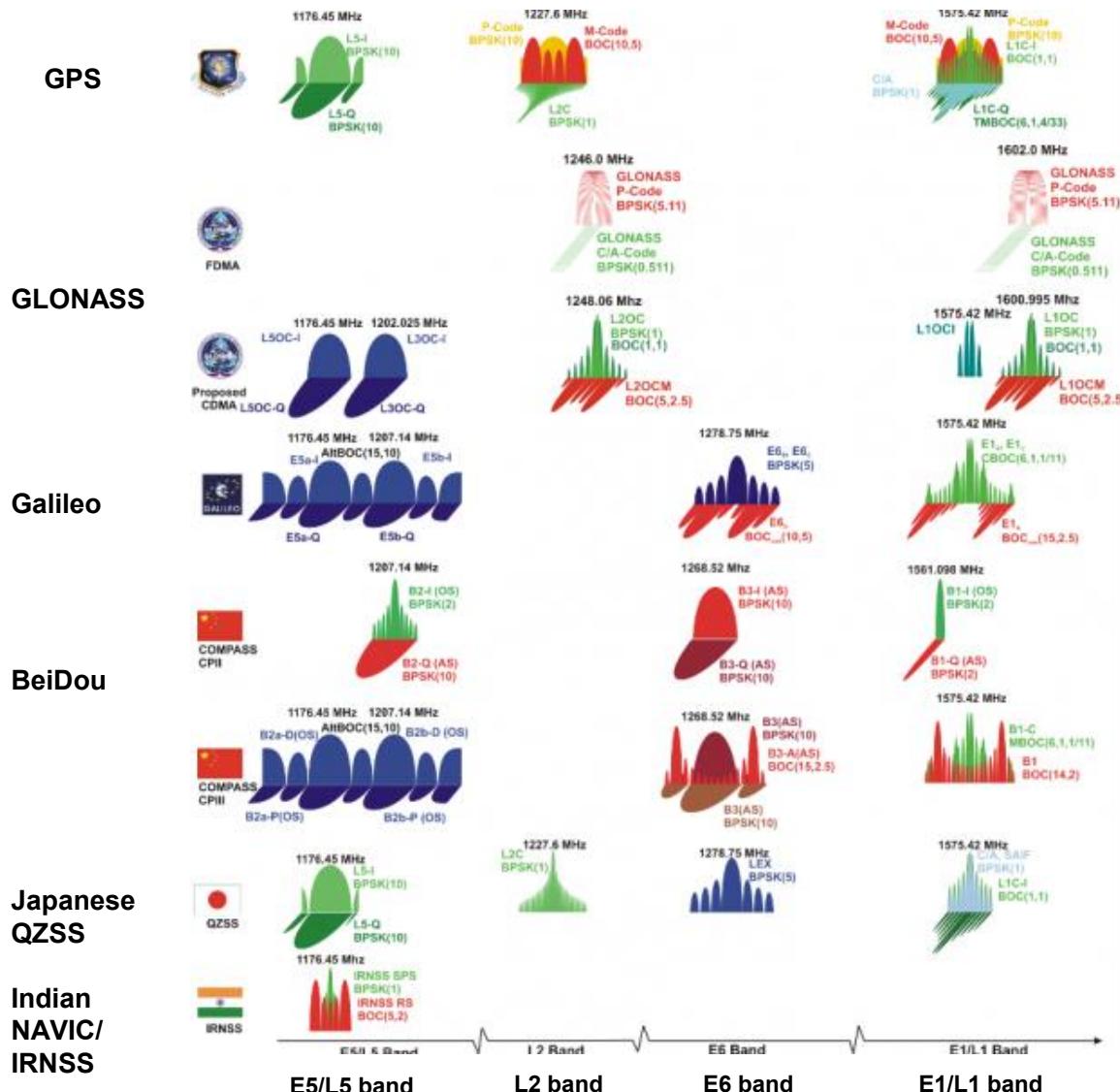


|                   | GPS    | GLONASS | Galileo | Beidou               | WAAS  | QZSS      | NAVIC  | EGNOS | MSAS  | GAGAN   |
|-------------------|--------|---------|---------|----------------------|-------|-----------|--------|-------|-------|---------|
| Operational       | 31     | 23      | 20      | 27                   | 2     | 3         | 5      | 2     | 2     | 2       |
| Nominal           | 24 MEO | 24 MEO  | 30 MEO  | 27 MEO & IGSO, 5 GEO | 3 GEO | 4 HEO     | 7 GEO  | 3 GEO | 2 GEO | 1-3 GEO |
| In full operation | 1995-  | 2011    | 2020    | 2020                 | 2008  | 2014-2017 | 2015 - | 2009  | 2007  | 2014 -  |

Currently augmenting GPS

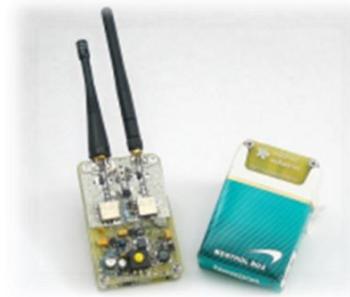
# GNSS frequency-wise (2)

## Frequencies



# GNSS shortcomings

- Signal's susceptibility to unintentional or malicious radio frequency interference (RFI) or jamming
- GNSS signals are typically too weak to be observable indoors
  - GNSS signals need to be augmented with external sensors to function accurately indoors
- Signal cannot provide an orientation solution easily, a feature that is indispensable in many vehicle navigation and guidance applications
  - GNSS and integrated navigation:
    - Inertial navigation systems (INSs) have been integrated with GNSSs with considerable success. This fusion between GNSSs and INSs is complementary: INS helps mitigate the shortcoming of the GNSS and vice versa. Other sensors are also commonly integrated with GNSS (e.g. other radio frequency (RF) signals, magnetometer, LIDAR, barometer)



S. Pullen, G. Gao, "GNSS Jamming in the Name of Privacy", Inside GNSS, March/April 2012, 34-43.

# Vulnerabilities & threat models related to GNSS (1)

| Layer                     | Threat type   | Example                                  |
|---------------------------|---|--|
| RF / Physical layer       | <b>Jamming</b>  | Intentional, unintentional, EW           |
| Signal structure layer    | <b>Spoofing, meaconing</b>                                  | Takeover attacks                         |
| Navigation solution layer | <b>Fault injection</b>                                      | Differential/RTK correction manipulation |
| System layer              | <b>Ephemeris manipulation, signal authentication bypass</b> | State-level threat                       |

# Vulnerabilities

1 kW wideband jammer  
can deny service to the  
best COTS GNSS  
receivers over a ~200 km  
(line-of-sight) effective  
range

## Intentional

- Jamming: transmission of a disruptive signal
- Spoofing: transmission of false GNSS signals to deceive a GNSS receiver
- Meaconing: re-transmitting genuine satellite signals with a short delay to create errors in the GNSS receiver
- Software attacks: targeting base stations or assistance data

## Challenges related to GNSS (2)

## Unintentional

- Severe space weather: ionospheric storms can cause GNSS errors

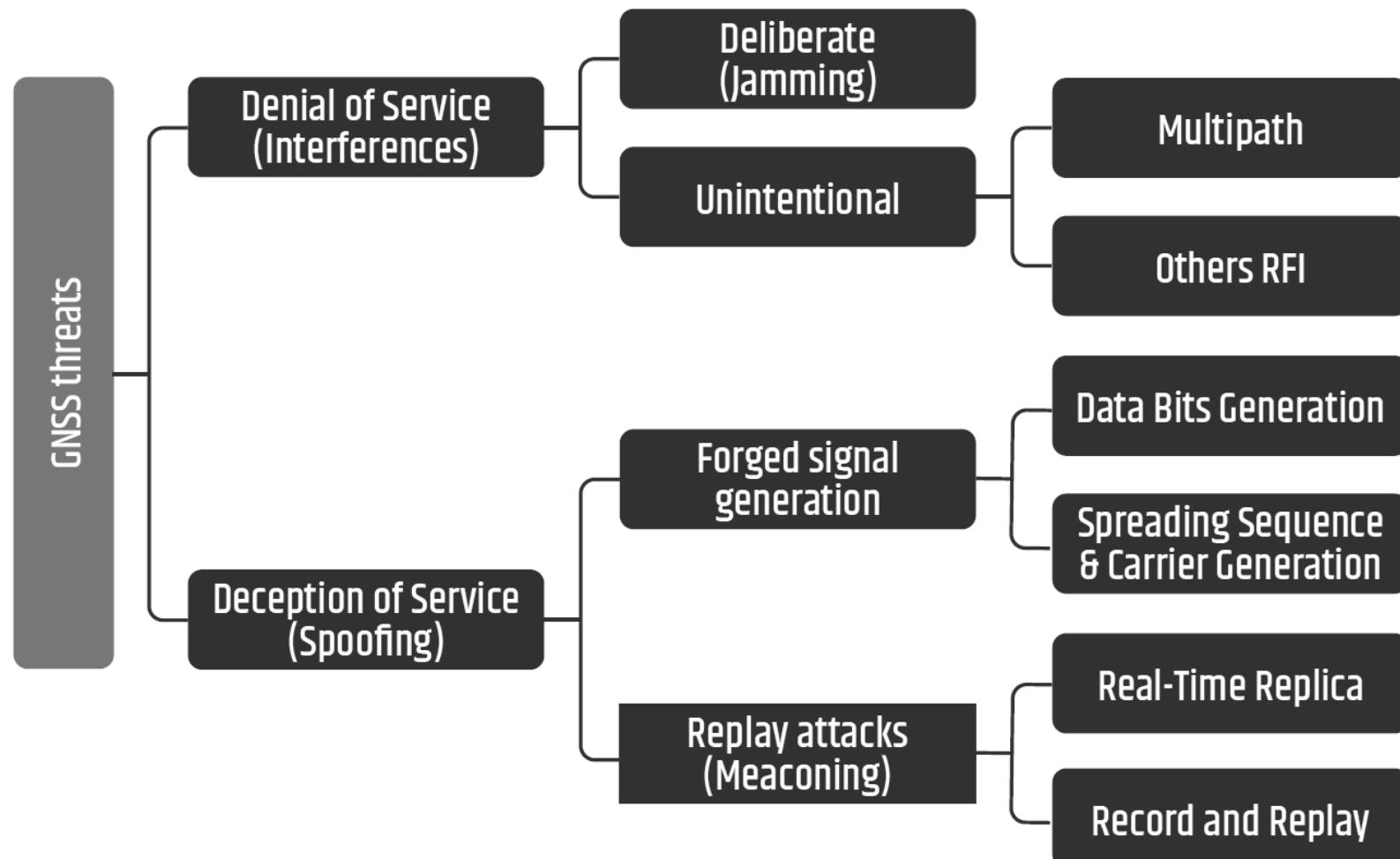
- Signal multipath reflections: no direct signal path from the satellite to the receiver's antenna
- Orbital data and clock errors
- Unintentional narrowband and wideband radio interference

# GNSS interferences (1)

| Interferences |               |                |                          |                                     |                           |  |   |
|---------------|---------------|----------------|--------------------------|-------------------------------------|---------------------------|--|---|
| Man-made      |               |                | Unintentional            |                                     | Channel-based             |  |   |
| Intentional   |               |                | Unintentional            |                                     | Space weather             | Multipath  | Other                                       |
| Jammering     | Spoofing      | Meaconing      | Adjacent channel         | Co-channel                          | atmospheric scintillation | line-of-sight + multipath non-line-of-sight only | fading shadowing doppler effects scattering |
| single band   | intermediate  | GNSS repeaters |                          |                                     |                           |  |   |
| multiband     | sophisticated |                | intermodulation products | radio resource allocation crosstalk |                           |  |   |

- Disruption of critical systems
- Potential safety and security risks

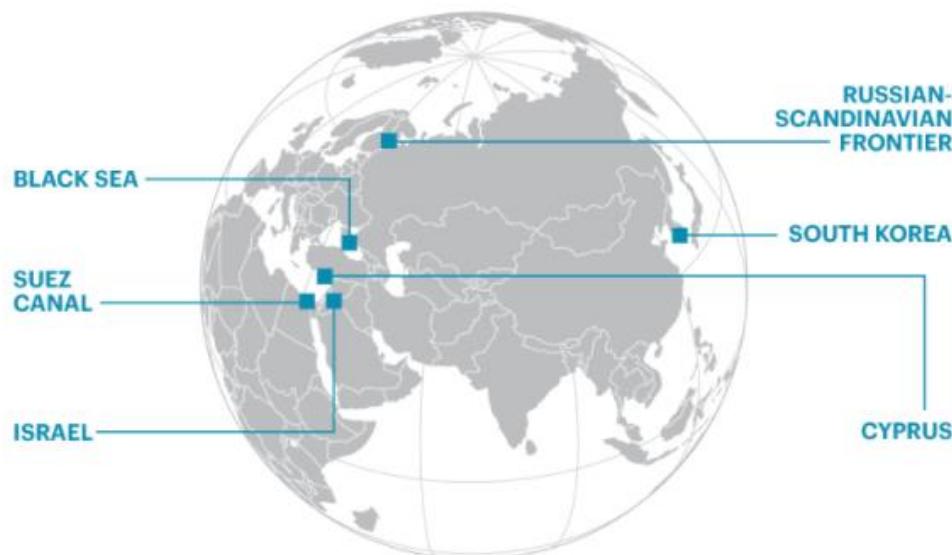
# GNSS interferences (2)



# Real-world incidents

- GNSS interference is no longer theoretical – despite illegal, it is operational, frequent and sometimes even strategic

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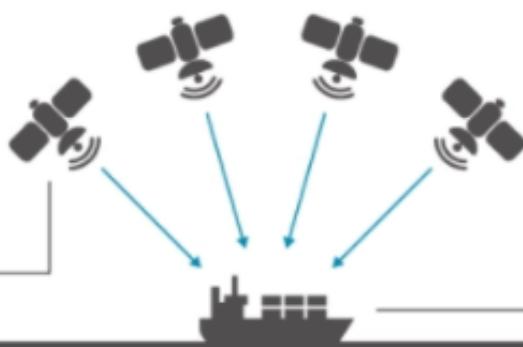
K. Dunn, “Mysterious GPS outages are wracking the shipping industry - For the global maritime shipping industry, spotty satellite navigation is a disaster waiting to happen”, FORTUNE magazine, January 22, 2020

# How Sinister Signals Stop Ships

The global positioning system, a network of satellites maintained by the U.S. Air Force, is widely seen as both reliable and nearly impregnable. But even the strongest satellite signals grow weaker as they get closer to earth's surface, and that creates opportunities for mischief. Here's how military forces, spies, and even criminal networks can interfere with GPS and other navigation systems.

## HOW THE GPS SYSTEM WORKS

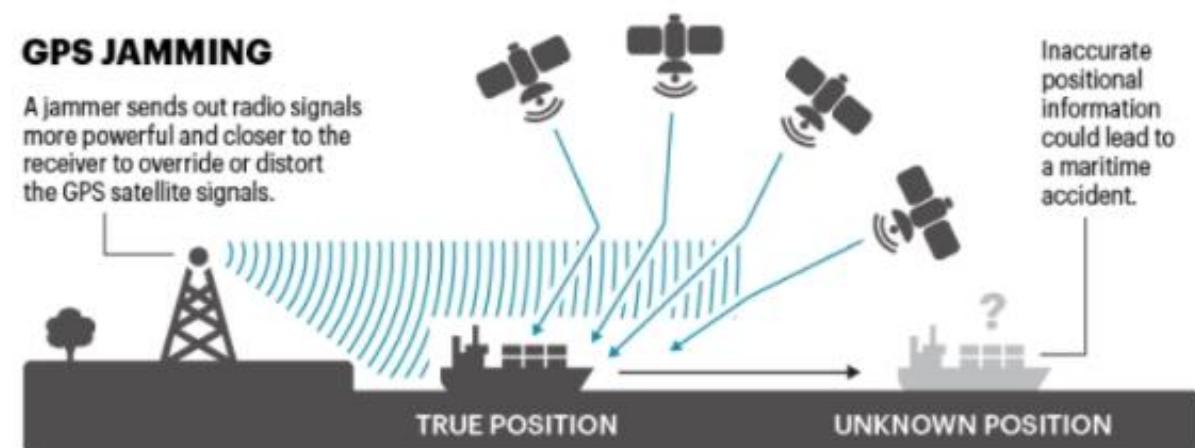
Satellites in orbit send radio signals detailing their position and the exact time.



The receiver on earth compares the time each signal was sent with the time it was received and calculates its distance from each satellite. From this data the receiver calculates its position.

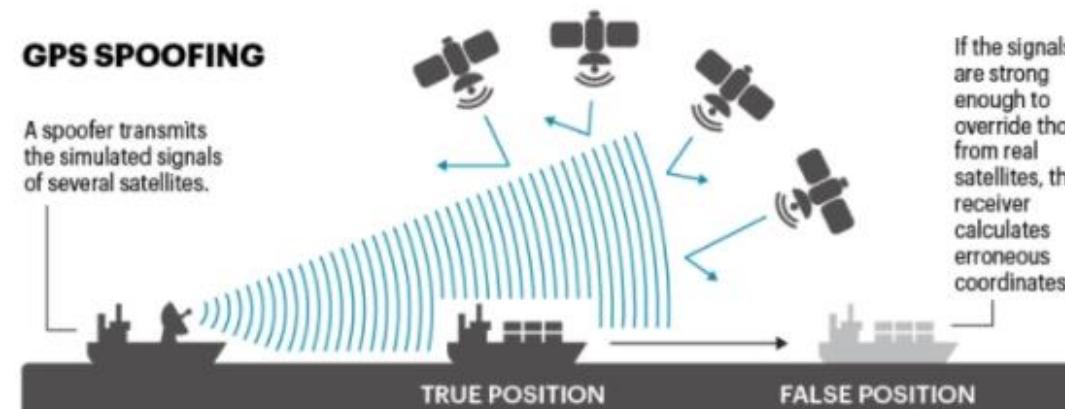
## GPS JAMMING

A jammer sends out radio signals more powerful and closer to the receiver to override or distort the GPS satellite signals.



## GPS SPOOFING

A spoofer transmits the simulated signals of several satellites.



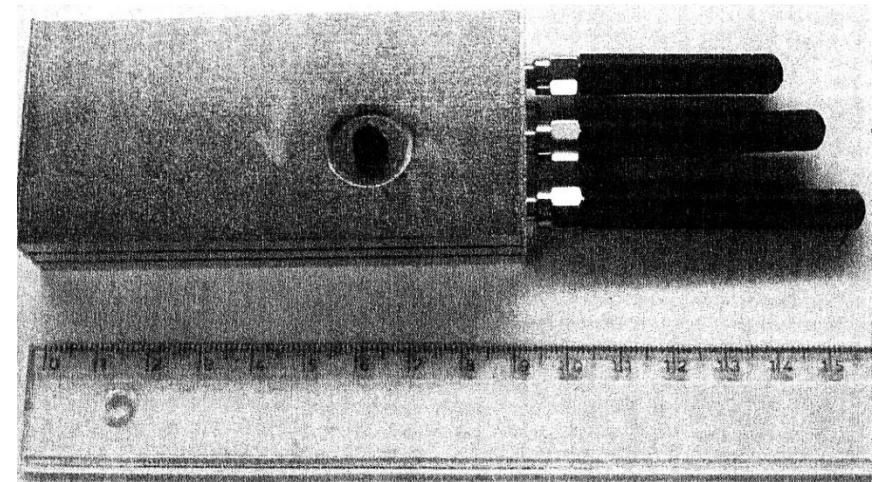
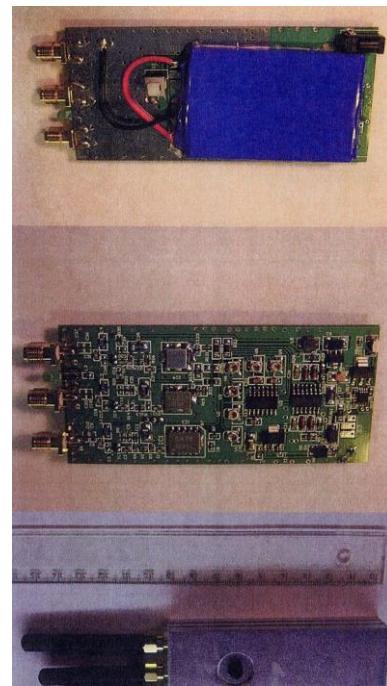
K. Dunn, "Mysterious GPS outages are wracking the shipping industry - For the global maritime shipping industry, spotty satellite navigation is a disaster waiting to happen", FORTUNE magazine, January 22, 2020

# GNSS vulnerability examples (1)



Newark Airport in 2009 –  
daily GPS signal disruptions  
*GPS jamming: No jam tomorrow*,  
*The Economist*, 2011

“Moottoripyöräjengiltä löytynyt outo laite ihmetytti poliisia.”  
*MTV Uutiset, Lokakuu 2011*



# GNSS vulnerability examples (2)

University of Texas at Austin spoofed a luxurious private yacht to showcase the threat, KVH Mobile World, 2014



KYBERASEET | Miina Rautiainen | 11.8.2017 klo 11:04

**Outoja GPS-ongelmia Mustallamerellä:  
laivan sijainti heitti yli 30 km sisämaahan -  
testasiko Venäjä uudenlaista asetta?**



JAA  
ARTIKKELI



Satelliittinavigoinnin ongelmat Mustallamerellä saattavat johtua Venäjän uuden GPS-häirintäjärjestelmän kokeiluista, kirjoittaa [New Scientist](#). Tämä voisi lehden mukaan olla ensimmäinen vihje uudenlaisesta sähköisestä aseesta, johon kaikilla on pääsy ilkeistä valtioista pikurikollisiin.

Kesäkuun 22. päivä Yhdysvaltojen merenkulkulaitos julkaisi tapausraportin. Venäläisen Novorossiysk-sataman edustalla olleen aluksen kapteeni oli huomannut GPS-laitteensa sijoittavan hänet väärään paikkaan, yli 52 kilometriä sisämaahan Gelendzhikin lentokentälle.

# GNSS vulnerability examples (3)

2018-12-17  
POSTET AV LIVE  
OFTEDAHL

## GPS-jamming: Luftambulansen mistet navigasjonssystemet på vei til pasient

Årsaken sto i sigarettenneren til en bil. Piloten var overlatt til det han så ut vinduet for å finne vi kritisk syke pasienten, skriver Bergens Tidende.



(Illustrasjonsfoto: Uffe Ørsted)

Tredje oktober i året rykket luftambulansen ut på et akutt oppdrag. Etter kun tre minutter var redningsmannskapet i luften på vei til en kritisk syk pasient.

Helikopteret flyv over, over E39 på Vellahelene. Piloten fulgte ruten som var plottet inn på et digitalt avanserte GPS-systemene viste dem hvor de var hele veien.

Akuttsentralen fulgte helikopterets ferd på sine skjermer. Slik kunne sentralen gi viktige beskjeder ankom skadestedet.

Plutselig forsvant helikopteret fra kartet. GPS-signalet var borte.

## GPS-häirintä ulottui Lappiin Naton sotaharjoituksen aikana – häirinnästä on epäilty Venäjää

Norjan viranomaisten mukaan vastaavaa häirintää on tullut Venäjältä. Suomen viranomaiset vaikenevat lähteestä.

Lentoliikenne 9.11.2018 klo 06.00 | päivitetty 13.11.2018 klo 12.18

Kuva: Jonathan Nackstrand / AFP



Nyheter

## Okända gps-störningar drabbar svenska flyg

PUBLISERAD 2019-02-05



sva och norska plan har drabbats av att deras gps-system slagits ut. Foto: Gorm Kallestad/NTB Scanpix

De okända störningssignalerna som misstänks ha slagit ut gps-system på flygplan i norskt luftrum de senaste månaderna har observerats även ovanför Sverige,

# GNSS vulnerability examples (4)

**Nettavisen Nyheter.**

[Ukraina](#)

## Flere europeiske rutefly rammet av GPS-forstyrrelser



BEKREFTET: Flyselskapet Finnair bekrefter overfor Nettavisen at flyene deres er blitt rammet av GPS-forstyrrelser de siste dagene. Foto: Jonathan Nackstrand (AFP)

**Finnair opplyser at GPS-en har vært ubruklig. - Kan være knyttet til russisk elektronisk krigføring, sier ekspert på russisk sikkerhetspolitikk.**

[Del](#)

▲ 10.03.22 15:00 ▾ 10.03.22 15:36

**DAGENS NYHETER.**

E-DN  
ARKIVET  
KORSORD

KUNDSERVICE  
SNILLE  
KUNDERBJUDANDEN

Nyheter Sverige Världen Ekonomi Kultur Sport Klimatet Ledare DN Debatt ⚙ Meny

VÄRLDEN

## Gps-störningarna runt Finland blir allt fler

PUBLICERAD 2022-03-10



Piloter från Finnair har rapporterat hur deras gps-system påverkats. Foto: Finnair/TT

**Finland har under flera dagar drabbats av störningar i gps-nätet. Från att först ha upptäckts vid landets östra gräns hade de på torsdagen också**

yle Utiset Areena Urheilu Valikko ☰

**Uutiset** Tuoreimmat Venäjän hyökkäys Sää Kotimaa Ulkomaat Talous

Lentoliikenne

**Lentokerhon vetäjä arvelee, että gps-signaalia Suomessa häiritään tahallaan – "Vaanallista touhua, jos signaali katkeaa huonoissa olosuhteissa"**

Alkuviikosta liikenne- ja viestintävirasto Traficom varoitti lentoliikennettä siitä, kuinka Suomen itärajalla on havaittu paikannuksessa häiriöitä. Traficom on kertonut selvittävänsä syitä häiriöiden taustalla. Savonlinnan Lentokerhon puheenjohtaja uskoo, että häiriöt on aiheutettu tahallisesti.



Savonlinnan Lentokerhon omistaman Cessna 172N Skyhawkin ohjaamon mittaristo kertoo GPS-signaalin häiriöstä. Kuva: Kati Rantala / Yle

KATI RANTALA, JUHO LIUKKONEN

10.3. 12:57

# Recent GNSS vulnerability examples

**Kaksi Finnairin konetta joutui palaamaan Virossa takaisin Suomeen GPS-häirinnän takia**

GPS-häirintä on yleistä, mutta useimmiten se ei aiheuta lentojen kääntymistä takaisin, kertoo Finnairin viestintäjohtaja.



Tartton lentoonteknä on erityisen altis GPS-häirinnälle, sillä siellä lähestyminen vaatii GPS-signaalia. Arkistokuva. Kuva: Sami Jumppanen / Korppaja

**Laura Kangas**  
27.4.9:15 · Päivitetty 27.4.10:05

**GPS-jamming er den nye hverdagen over Finnmark**

Frekvensforstyrrelser skjernærmet daglig i Finnmark. Politimesteren sier situasjonen er alvorlig.



10.000 fot i lufta over Øst-Finnmark mäter norske myndigheter frekvensforstyrrelser fra Russland. FOTO: SEBASTIAN FAUGSTAD / NRK

**Maatalous**

**Traktorit sekosivat itärajalla – piirtävät nyt peltoon vihreitä raitoja**

Viljely itärajalla on ongelmissa, koska traktorit eivät saa oikeaa paikatietoa GPS-paikannusjärjestelmästä. Häirintä tulee ilmeisesti Venäjältä.

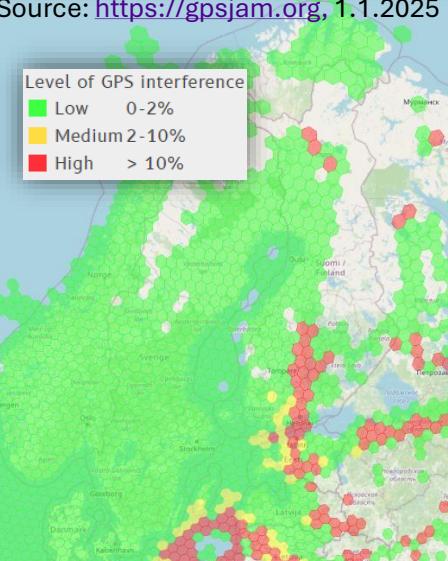


Kari Pekosen pelloille jää vihreitä raitoja satelliittipaikannuksen ongelmien vuoksi.

**Kalle Schönberg**  
7.6.8:51 · Päivitetty 7.6.10:14

**Source: <https://gpsjam.org>, 1.1.2025**

Level of GPS interference  
 Low 0-2%  
 Medium 2-10%  
 High > 10%




Ett flygplan över Kristianstad anmälde störningar i GPS-systemet. Foto: Janerik Henriksson/TT

**SATELLIT**

**Nya GPS-störningar i sydöstra Sverige**

0:39 min · [Dela](#)

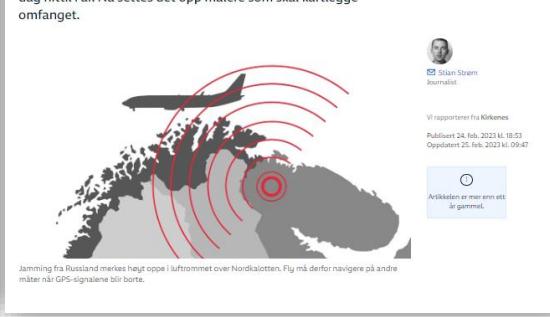
Publicerat förra måndagen kl 12:39

- Störningar i GPS-systemet fortsätter och så sent som i onsdags så upplevde ett flygplan störningar som rapporterades till Transportstyrelsen, det rapporterar [SVT](#) C.
- Flygplanet flög över Kristianstadstrakten och de tidigare störningarna har också märkts i södra Sverige och sydöstra Östersjön, framför allt nattetid.

**Andrea Jilder**  
[andrea.jilder@sverigesradio.se](mailto:andrea.jilder@sverigesradio.se)  
P4 Blekinge

**Kraftig økning av GPS-jamming over Finnmark**

Russisk GPS-jamming har rammet Øst-Finnmark nesten hver dag hittil i år. Nå settes det opp målere som skal kartlegge omfanget.



Jamming fra Russland merkes heftig opp i luftrommet over Nordkalotten. Fly må derfor navigere på andre måter når GPS-signalene blir borte.

**Stian Strem**  
Journalist

Vi rapporterer fra Kirkenes

Publiserat 24. feb. 2023 kl. 18:53  
Oppdatert 25. feb. 2023 kl. 09:47

**Artikkelen er mer enn ett år gammelt.**

**Nyheter**

**Långvariga GPS-störningar över Gotland**

TT  
Publicerad 2025-01-17

[Mejla](#) [Dela](#) [Spara](#)



Flygtrafik och sjöfarten påverkas av GPS-störningarna som har återkommit över Östersjön under lång tid. Arkivbild Foto: Jonas Ekströmér/TT

Gotland och delar av Öland har i minst 60 dagar i rad omfattats av stundtals kraftiga GPS-störningar som påverkar fartyg och flygtrafik, skriver Expressen.

**Merenkulkku**

**Venäjän varjolaivaston outo ympyräleikki lähellä Suomen merirajaa hämmäntää**

Meriliikennekartoilla näyttää siltä, kuin alukset tanssisivat tietkajenkka Suomen merirajan tumumassa. Oikeasti aluksia ei paikalla ole.



Kuvaakaappaus MarineTrafficin sivustolta tilastaaamuna 20.5.2025. Kuva näkyy Venäjän varjolaivaston muodostama ympyrä Suomenlahdella. Kuva: Kuvaakaappaus MarineTraffic-sivustolta

**Suomessa "ennennäkemättömiä" gps-häiriötä – tänne ne keskittyvät**

Häiriöiden määrä on kasvanut Suomessa kahden viime vuoden aikana.

[JAA](#) [TALLENNAA](#)

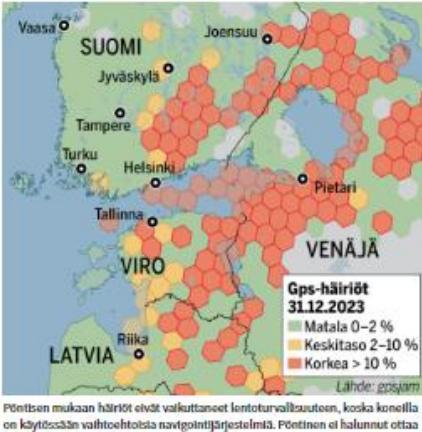


Gps-häiriöt seuravien sivuston ylläpitoja pitää häiriöiden määrää poikkeuksellisen suuren. KUVA: ISOMI REKOMÄÄ / LEHTIKUVA, KUVAAKAIPMUS / X, ANNA DAMMERT / TRAFICOM

**SATELLITIITIPIAKKANUSJÄRJESTELMÄ** GPS-tila esittyy sunnuntaina häiriöitä Itä- ja Kaakkois-Suomessa, Tukkinen- ja Viestintävirasto Traficomista kerrotaan.

Häiriöt tulivat alemminkin ilmi avointen laitteen GPS-dataa keraavilta GPS-sivustoilta. Samaten sivuston mukaan häiriötä ilmeni myös muun muassa Savon ja Pohjois-Karjalan seudulla maanantaina.

Tiedot häiriöistä perustuvat lentokoneiden tekemien ilmoituksien, joita tuli sunnuntaina kohtalaisen laajalta alueelta, ilmailusta vastaava johtaja Jari Pöntinen Traficomista kertoo.

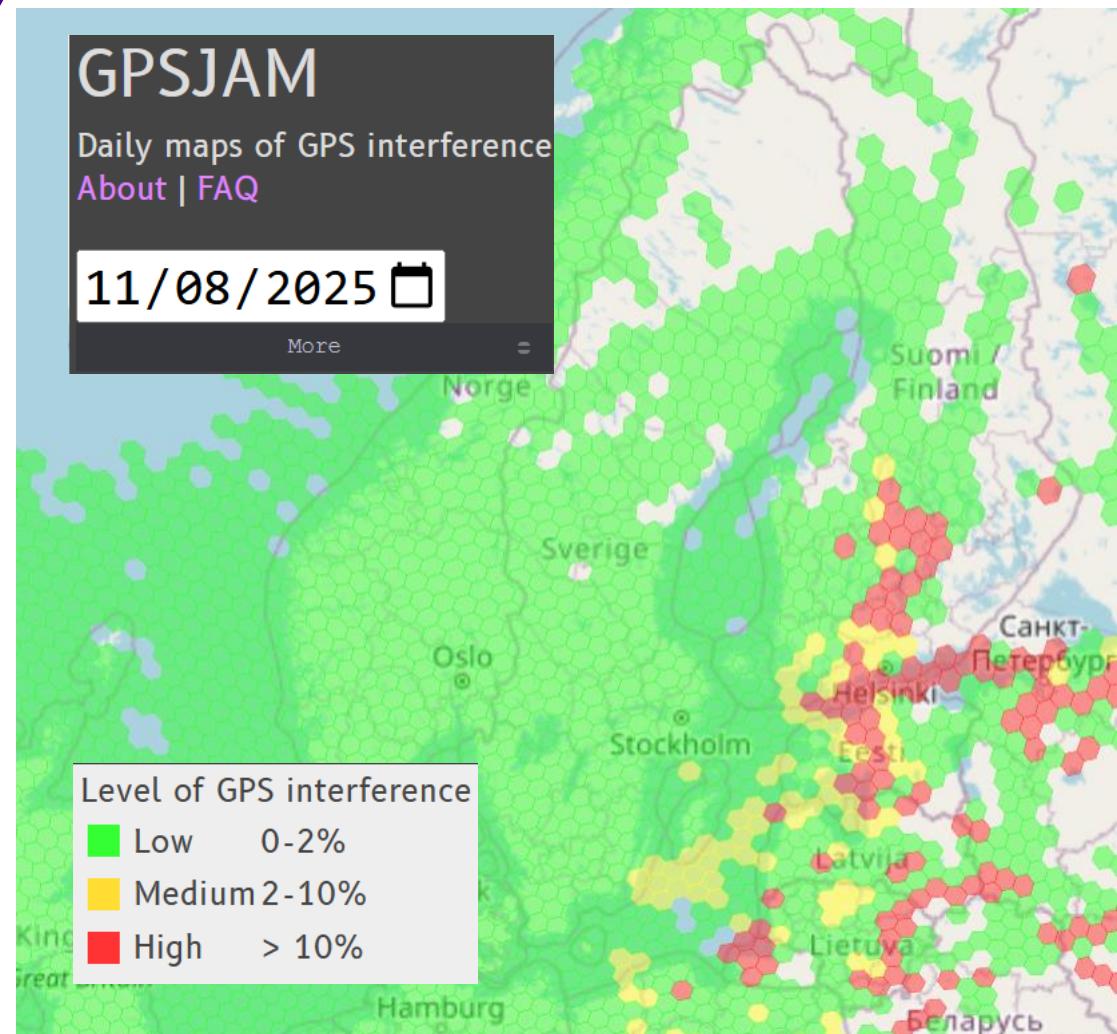


Pöntisen mukaan häiriöt eivät vaikuttaneet lentotarvalluuteen, koska koneilla on käytössään valtioneitoista navigointijärjestelmä. Pöntinen ei halunnut ottaa kantaa häiriöiden syyistä.

# Interference monitoring (1)

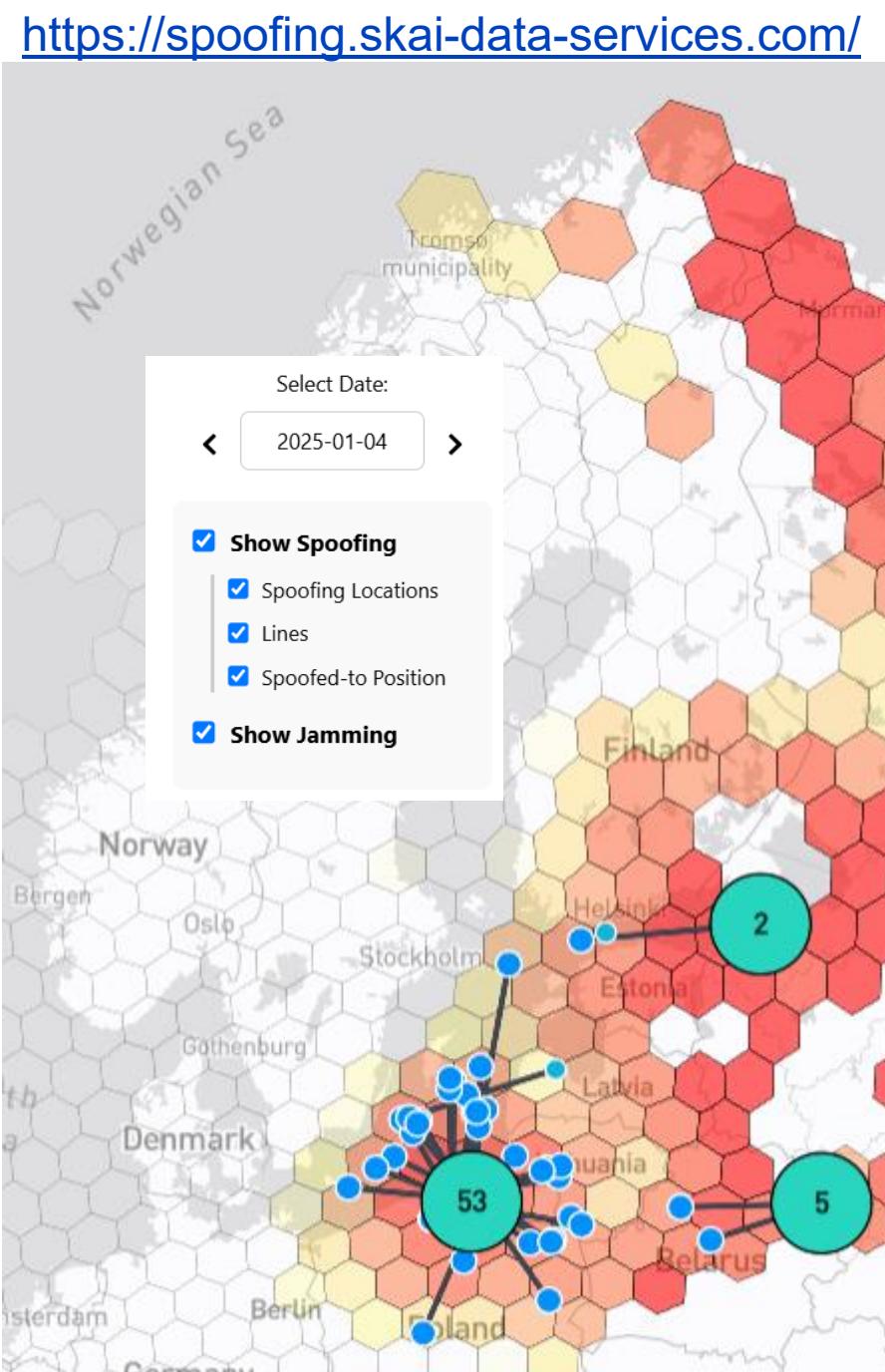
- [gpsjam.org](https://gpsjam.org/) aggregates ADS-B aircraft data to infer GNSS signal disruption affecting aviation navigation systems
- Uses C/N<sub>0</sub> degradation patterns reported by aircraft avionics to detect areas where jamming is ongoing
- Provides near real-time heatmaps of interference globally, updated continuously
- Shows persistent GNSS denial zones in regions of geopolitical tension, conflict operations, or military training exercises
- Civil aviation is already navigating in contested PNT environments

<https://gpsjam.org/>



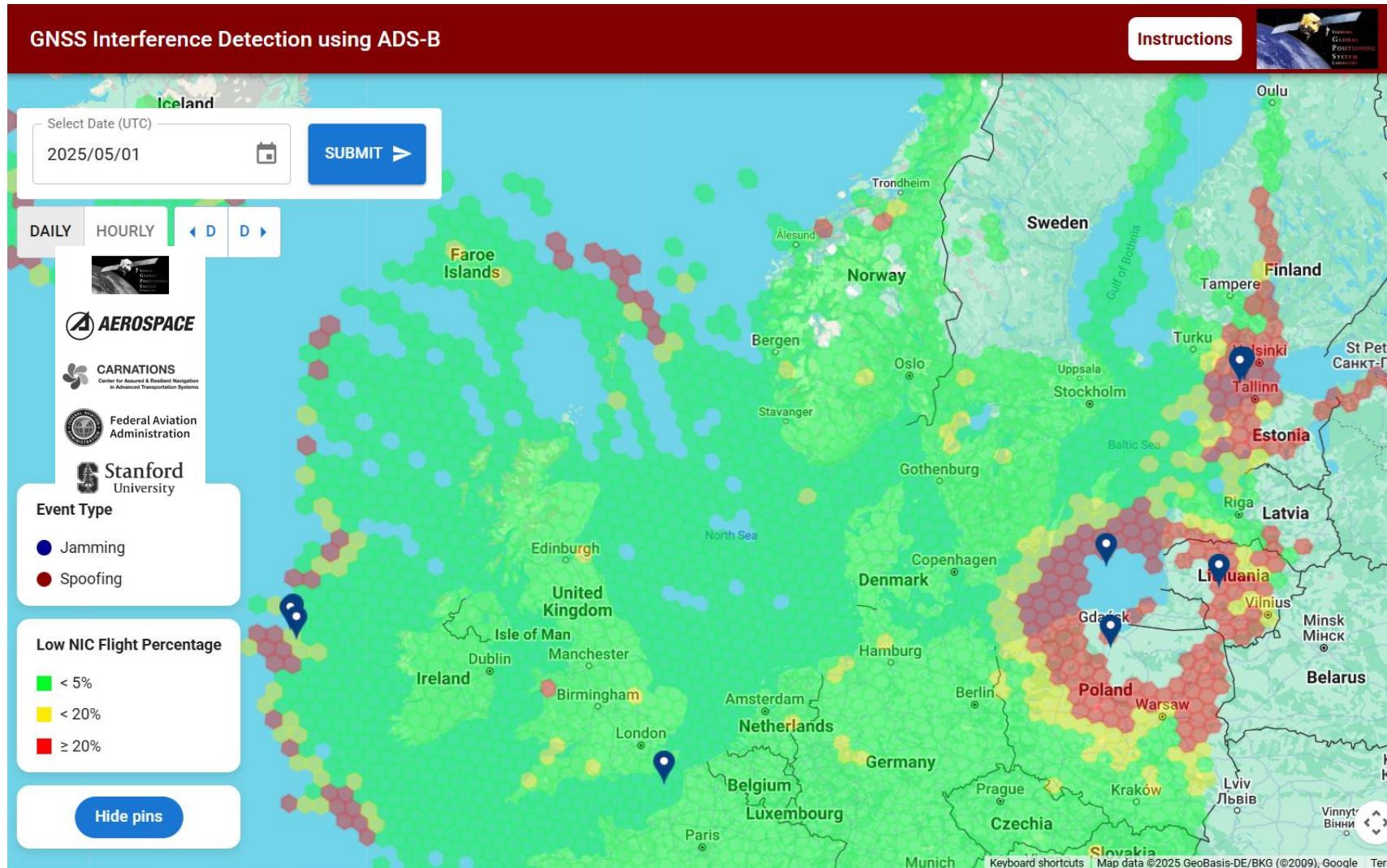
# Interference monitoring (2)

- Real-time GPS interference mapping service by SkAI Data Services and Zurich University of Applied Sciences
  - ADS-B detected GNSS spoofing (blue dots) and jamming (coloured hexagons) from commercial aircraft (Jan 4, 2025)
- The map displays clusters that indicate areas where spoofed (or "fake") GPS positions of aircraft have been detected
  - the numbers within each cluster show how many flights were spoofed at that specific location
- The markers in blue markers represent the positions of aircraft just before they were spoofed
  - The lines connect these real positions to their corresponding spoofed (fake) locations
- Areas of potential GPS jamming or radio frequency interference indicated by colored hexagons



# Interference monitoring (3)

Similar tool has also been developed by the Stanford University GPS Lab



rfi.stanford.edu

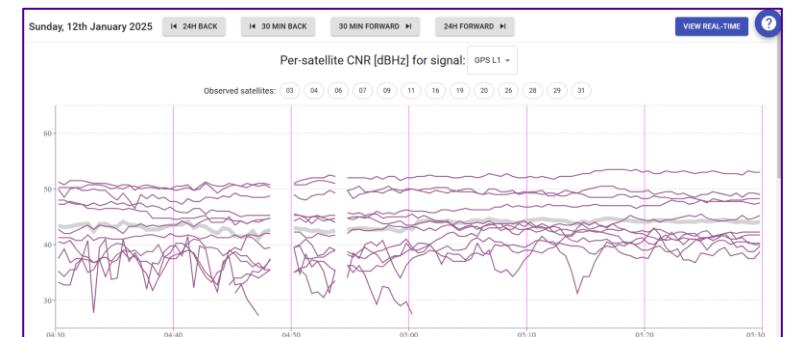
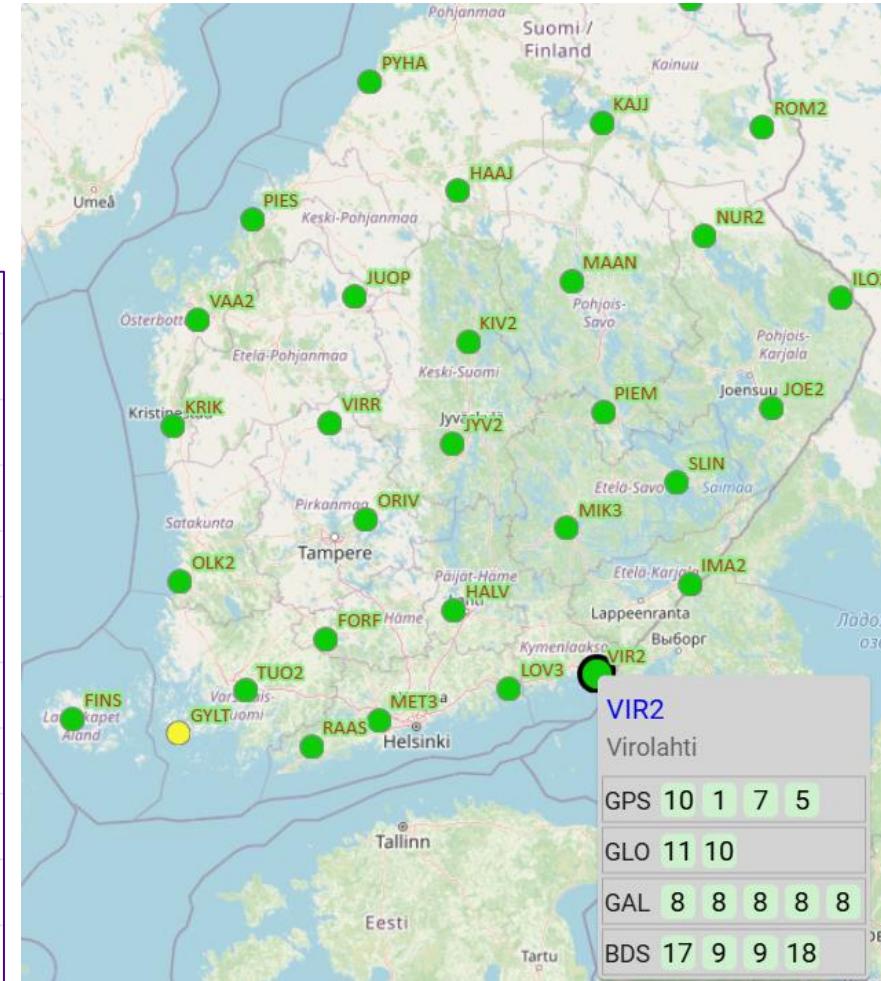


# GNSS Finland monitoring service

- GNSS-Finland Service bases on the national GNSS reference station network FinnRef maintained by the National Land Survey of Finland
  - Data from the network is analyzed by the service in real time
- Signals monitored at different stations along with signal strength estimation parameters
- The service continuously monitors strength of each signal and produces a signal quality indicator as "good", "satisfactory" or "poor"

<https://gnss-finland.nls.fi>

|              |
|--------------|
| GPS L1       |
| GPS L1C      |
| GPS L2C      |
| GPS L5       |
| GLONASS G1   |
| GLONASS G2   |
| Galileo E1   |
| Galileo E5a  |
| Galileo E5b  |
| Galileo E5ab |
| Galileo E6   |
| BeiDou B1    |
| BeiDou B1C   |
| BeiDou B2a   |
| BeiDou B3    |

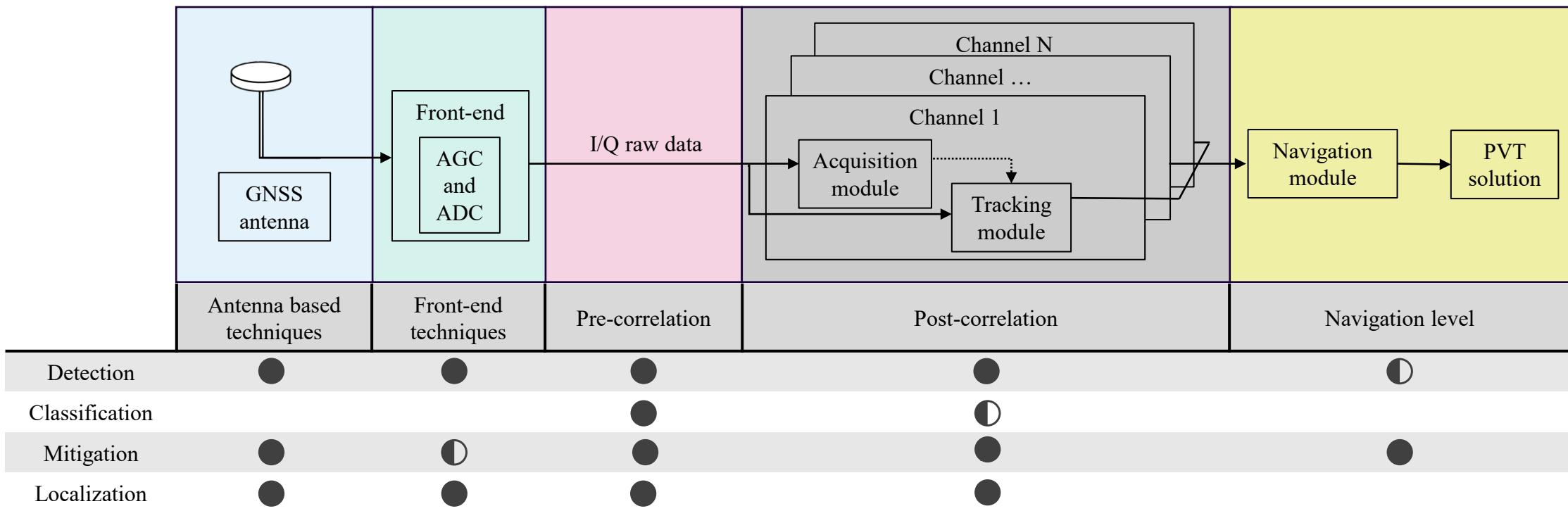


# Principles of Resilient PNT

Resilience = Detect +  
Withstand + Recover

| Defense layer      | Examples   |
|--------------------|--|
| Signal & RF layer  | Interference monitoring, adaptive antennas, nulling                    |
| Measurement layer  | Receiver Autonomous Integrity Monitoring (RAIM/FDE/ARAIM)              |
| System layer       | Signal authentication (Galileo OSNMA), frequency and system redundancy |
| Multi-source layer | GNSS + 5G + Wi-Fi + IMU + maps + other sensors                         |

# GNSS interference mitigation possibilities



GNSS receiver stages and typical places for interference detection, classification, localization, and mitigation

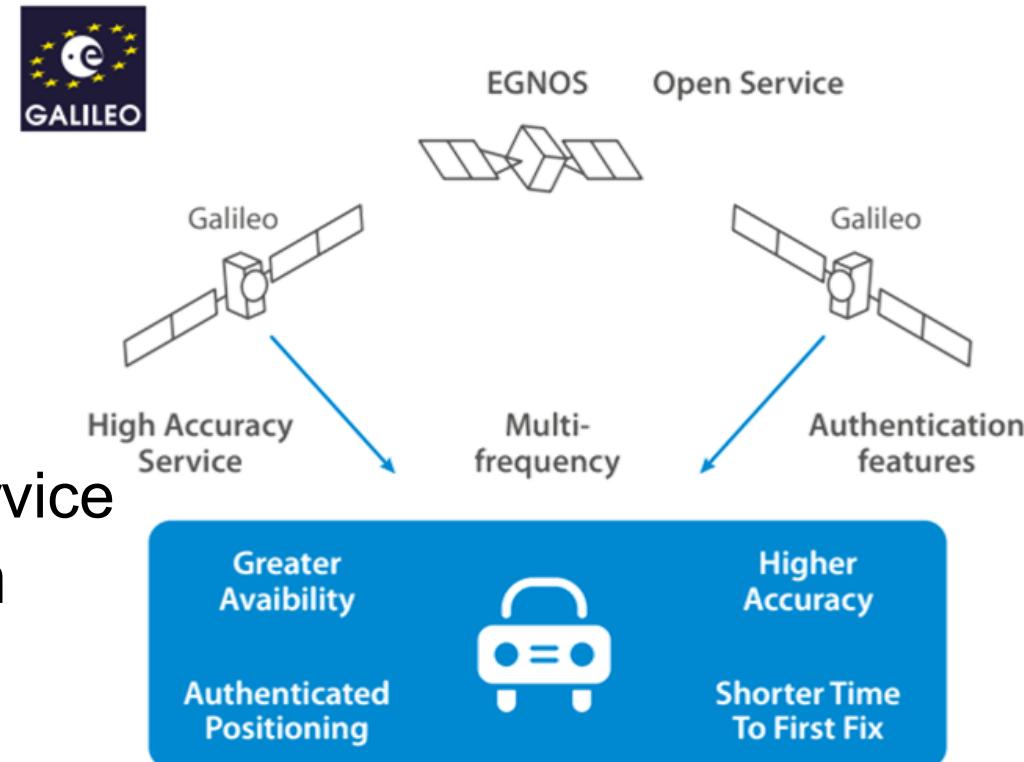
# Interference management techniques

| Class                    | Approach and algorithms  | Strengths   | Limitations  |
|--------------------------|--|---|--|
| Antenna based techniques | Use of <b>antenna array</b> to filter out interference signals, for example using angle of arrival.              | Can handle different types of interferences.<br>Outstanding performance.                | Requires <b>multiple receiver antennas</b> , high hardware complexity, sometimes export-controlled.        |
| Front-end techniques     | Process signals before the ADC, e.g., <b>Automatic Gain Control</b> (AGC).                                       | Can handle different types of interferences.  | Poor performance for low power spoofing.   |
| Pre-correlation          | Uses <b>raw received signal features</b> ; can be signal-processing based or ML-based (e.g., RF fingerprinting). | Early detection and classification; high detection probability before filtering stages. | Limited mitigation/localization; cannot identify affected satellites; ML requires large training datasets. |
| Post-correlation         | Use <b>signal after correlation</b> (SQM, $C/N_0$ monitoring, peak monitoring, scatter diagrams)                 | Can detect, mitigate, localize, identify genuine vs spoofed signals.                    | Struggles with induced spoofing; ML may require large datasets.  |
| Navigation level         | Uses multi-signal, multi-satellite, multi-frequency and multi-receiver <b>consistency tests</b> .                | Integration with sensor fusion is intuitive and well developed.                         | Long processing time; <b>delayed interference response</b> .   |

# Emerging countermeasures & authentication (1)

- The Galileo system, once fully operational, will offer eight high-performance services worldwide:
  - Open Service (OS)
  - Open Service Navigation Message Authentication (OSNMA)
  - Public Regulated Service (PRS)
  - High Accuracy Service (HAS)
  - Timing Service (TS)
  - Signal Authentication Service (SAS)
  - Search and Rescue Service (SAR)
  - The Galileo Emergency Warning Satellite Service
- Signal authentication in the Galileo system
  - Ensures trust in positioning data
  - Detects and prevents spoofing

[European GNSS Service Center](#)  
[EUSPA EO and GNSS Market Study, European Commission 2024.](#)



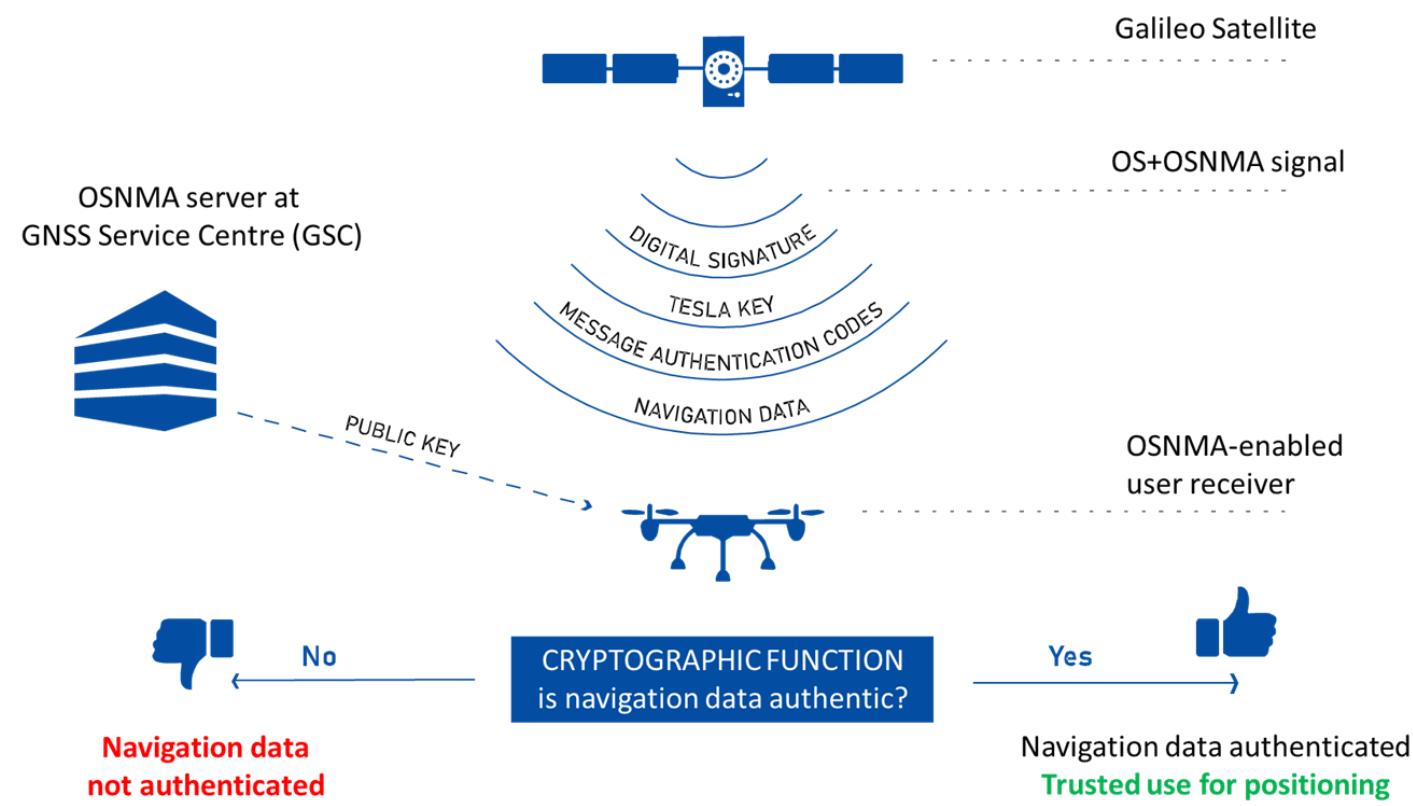
# Emerging countermeasures & authentication (2)

| Service                        | Description   |
|--------------------------------|---|
| Open Service (OS)              | Free for all users; provides positioning, navigation, and timing globally.  |
| High Accuracy Service (HAS)    | Offers centimeter-level accuracy ( $\approx 20$ cm) for free since Jan 2023.  |
| Commercial Service (CS)        | Provides encrypted signals and additional data for commercial applications.   |
| Public Regulated Service (PRS) | Encrypted, robust service for authorized government and critical infrastructure users.  |
| Safety of Life Service (SoL)   | Designed for applications requiring integrity and reliability (e.g., aviation).   |
| Search and Rescue (SAR)        | Integrated with MEOSAR; enables faster detection and location of distress signals.  |
| OSNMA                          | Open Service Navigation Message Authentication: Provides authentication for navigation messages to enhance security.  |
| CAS                            | Commercial Authentication Service: Offers advanced authentication for high-security commercial applications.  |
| New Features                   | HAS free access for high precision positioning; PRS signals broadcasting started in 2024; Ground segment upgrade for enhanced cyber protection and readiness for Second Generation (G2) satellites. |

***Security moves from trusting the signal to trusting the solution***

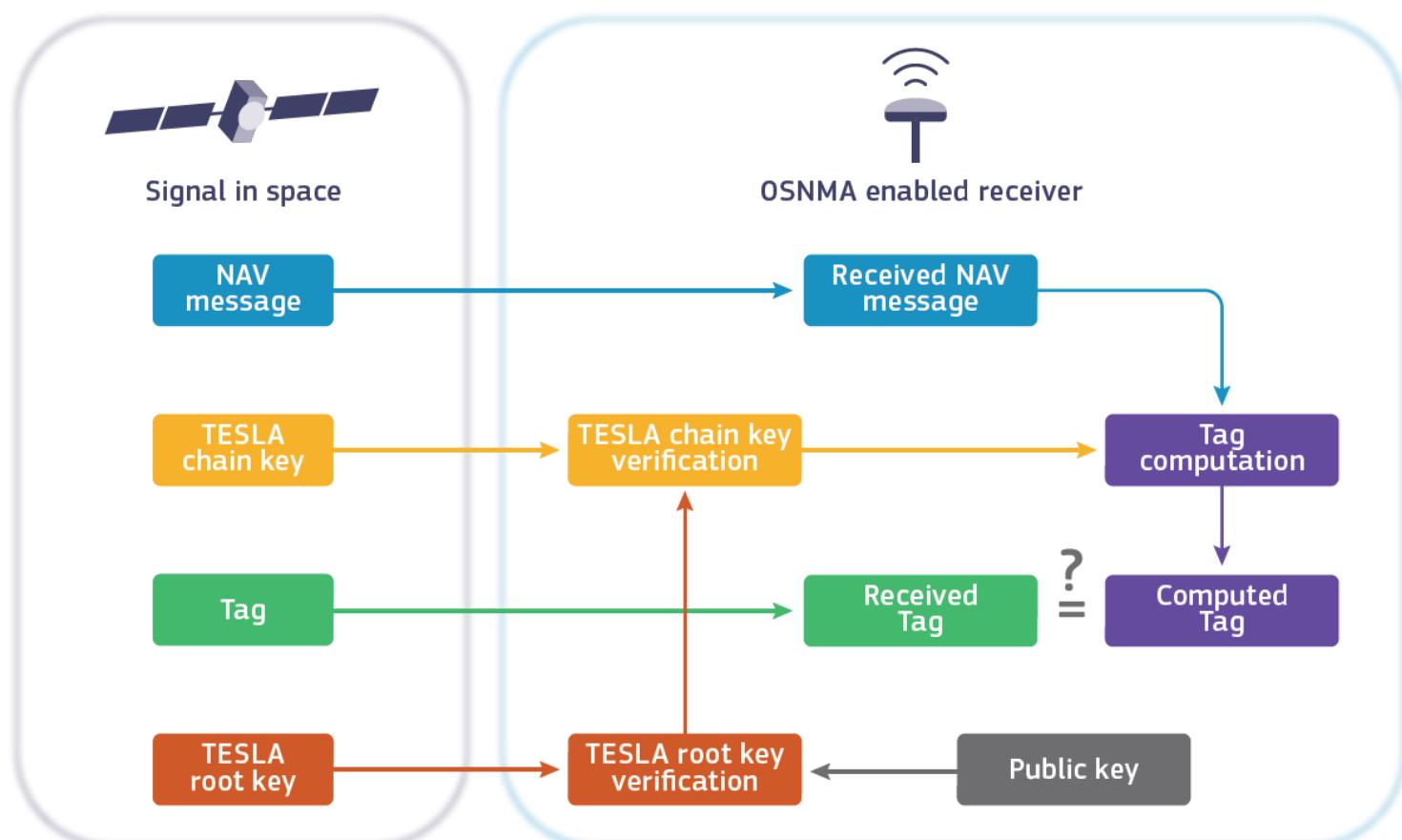
# Open Service Navigation Message Authentication OSNMA (1)

- OSNMA is a new feature of the Galileo Open Service which enables users to **verify that the navigation data they receive originated from the Galileo satellite and has not been modified**
- OSNMA is **now available for testing** by receiver manufacturers and application developers



# Open Service Navigation Message Authentication OSNMA (2)

- Navigation data are verified through the computation of a truncated Message Authentication Code (MAC), named **tag**, which is compared against a **received tag**.
- The tag is computed with a **key**, released after the tag. To ensure the timely reception of OSNMA data, **time synchronization** to GST is required.
- The key is part of a TESLA chain, and can be used to derive previous keys, as the **TESLA root key**.
- The TESLA root key is verified with a **public key** through a digital signature algorithm.

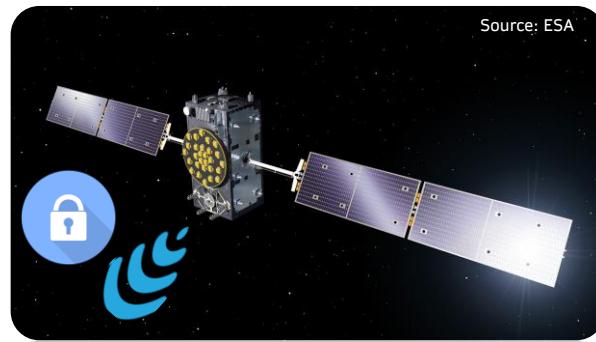


# Real-world resilience testing important

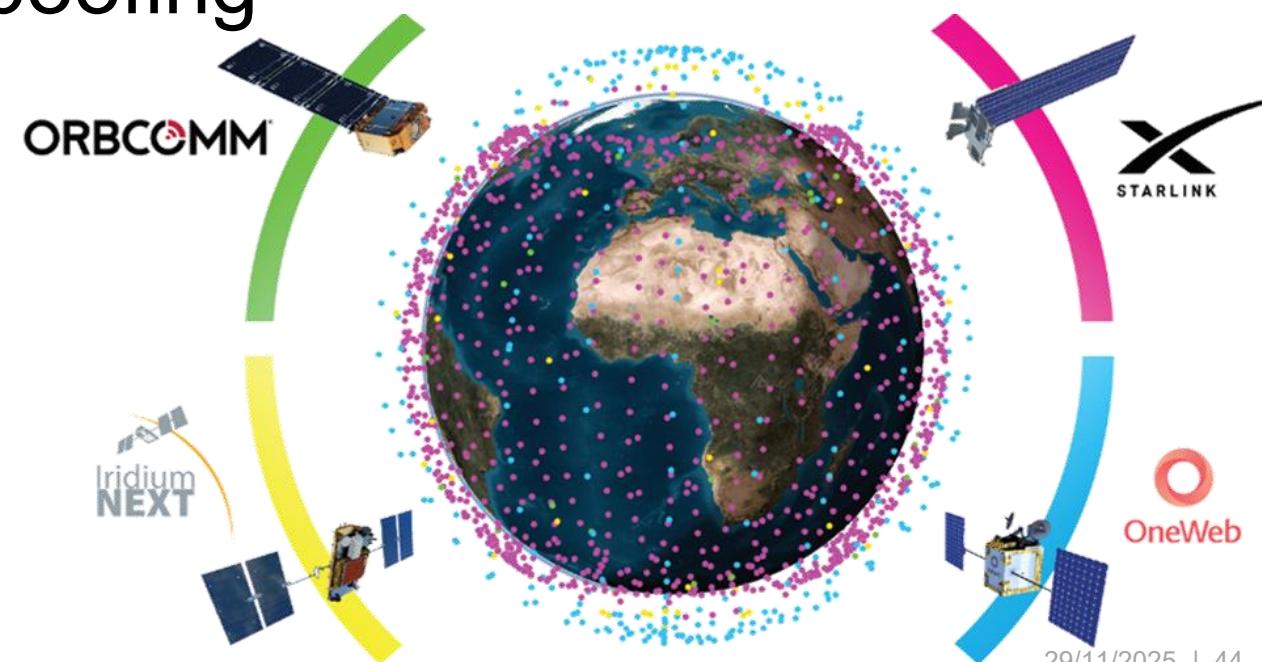
- For example the Jammertest in Norway: controlled GNSS interference, also in open air ([www.jammertest.no](http://www.jammertest.no))
- Realistic conditions, realistic consequences
- Cross-sector collaboration
- Data to drive PNT innovation & also policy



## Multi-layer PNT & LEO-based PNT



- Resilient PNT is becoming inherently multi-layered, authenticated, and intelligent
- Interference management and authentication to fight GNSS jamming and spoofing
- Robustness and redundancy also via **Low Earth satellite systems**
- Terrestrial systems (**5G/6G, WLAN** etc)



# LEO-PNT to complement GNSS

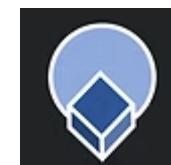
Celeste is the the LEO-PNT In-Orbit Preparatory Phase (IOPP) of the FutureNAV Programme at ESA

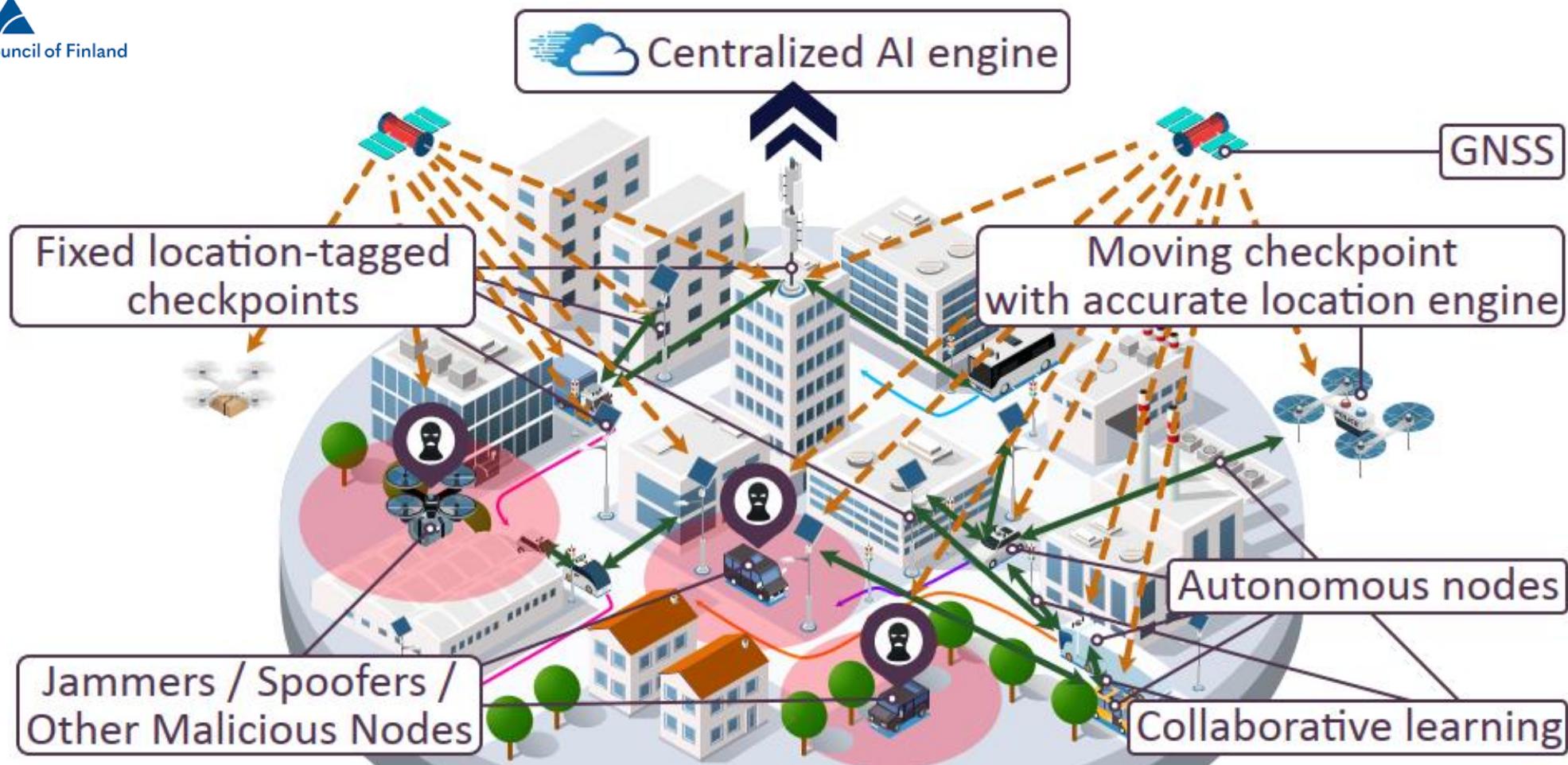
A LEO PNT complement to the backbone Galileo and EGNOS infrastructures within a global EU PNT architecture will significantly enhance the resilience and accuracy of and the derived PNT services



Operating closer to Earth, LEO-PNT will support precise and robust PNT services, even in environments subject to jamming, interference, or degradation, thus ensuring reliable access to critical geolocation and timing information in any scenario

National project  
INCUBATE on LEO PNT,  
funded by Technology  
Industries Finland  
(Aalto University,  
Tampere University,  
University of Vaasa,  
Finnish Geospatial  
Research Institute)





## CONCEPT OF PROJECT RESILIENT

Distributed AI for enhanced security in satellite-aided wireless navigation

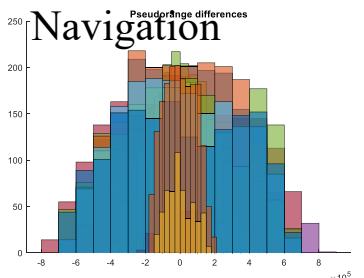
# Collaborative Interference Mitigation and Robust Positioning

## THRUST I

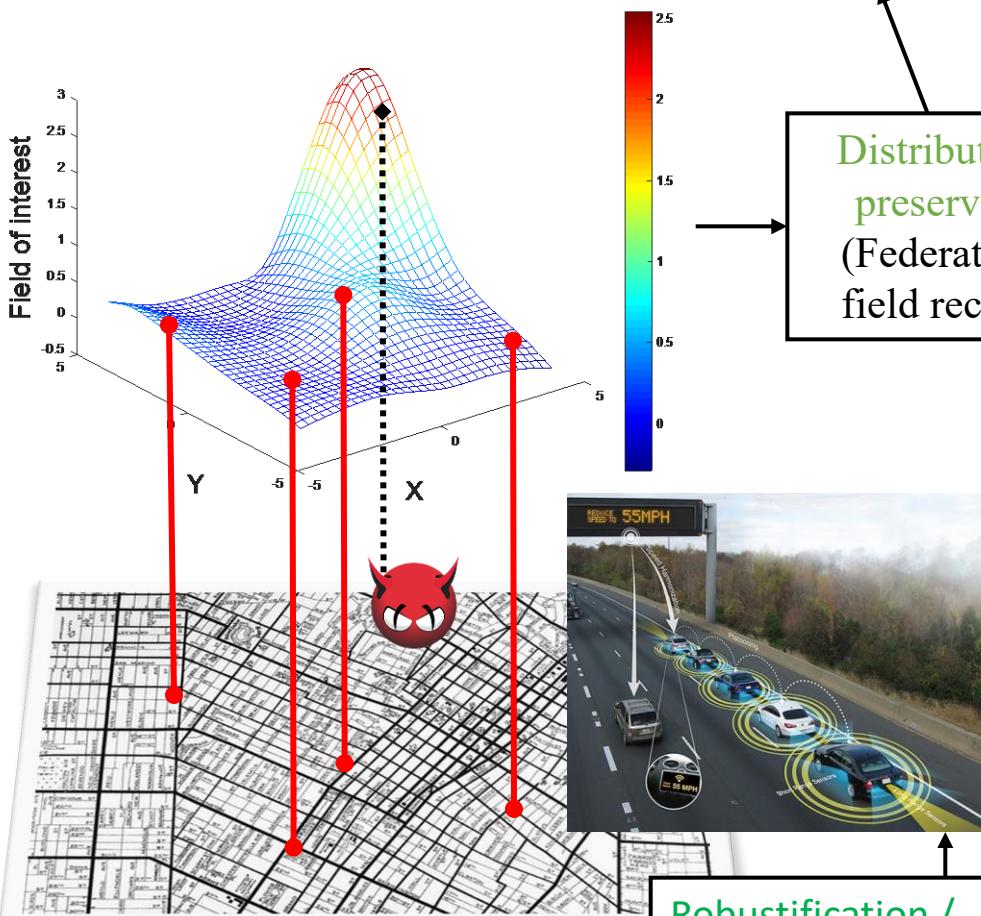
RF fingerprinting for  
interference  
management  
(hybrid data/model-  
driven)

Pre-  
correlation

Post-  
correlation



Field of interest  
(Threat fingerprint or threat probability)



Distributed, privacy-  
preserving sensing  
(Federated Learning  
field reconstruction)

Threat localization  
and tracking  
(Active learning)

Meta-learning  
(Task level knowledge)

Robustification /  
Collaboration with fixed anchors and  
exploiting strong interferers  
(Reinforcement learning/ Factor Graph  
Optimization)

## THRUST III

- Optimized robust positioning using **Factor Graph (FG)** in combination with threat detection
- Adaptive positioning strategies using **Reinforcement Learning (RL)**

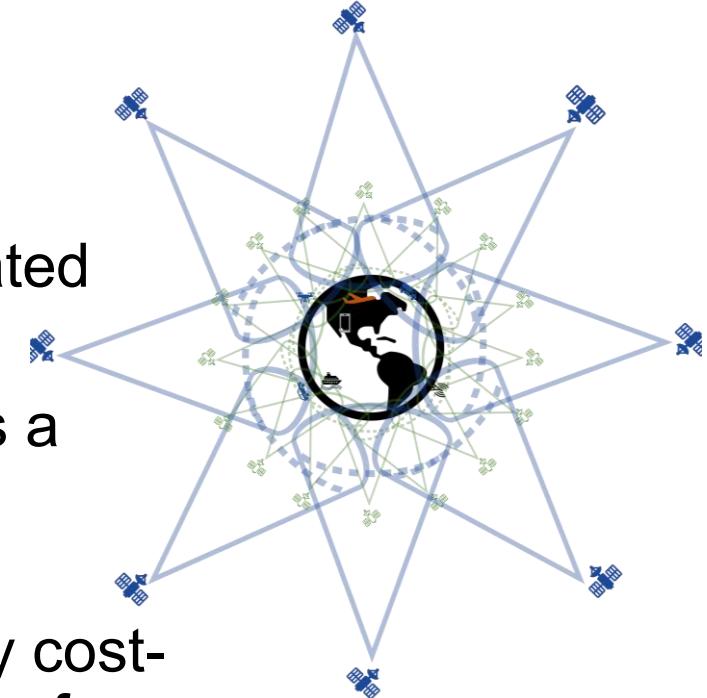


# Key takeaways (1)

- GNSS receivers should exploit **multi-constellation multi-frequency diversity** for robust PNT services
- Modernized GNSS signals and services such as Galileo E1 **OSNMA** and Galileo E6 **CAS** encryption should be utilized to protect users from spoofing attacks
- Intelligent advanced **algorithms at tracking and measurement layers** will make future receivers better resilient against adverse GNSS vulnerabilities
- The Standards Working Group for Resilient PNT User Equipment (**P1952**) in **IEEE** is working towards refinement and development of 'Resilient PNT Conformance framework'
- **Low-cost antenna array solutions** can improve PNT resilience in the form of interference/spoofing source detection, localization, and mitigation
  - By multi-element antennas we can toughen GNSS receivers enough to withstand 1 kW wideband Gaussian jammer at a distance of 2 km

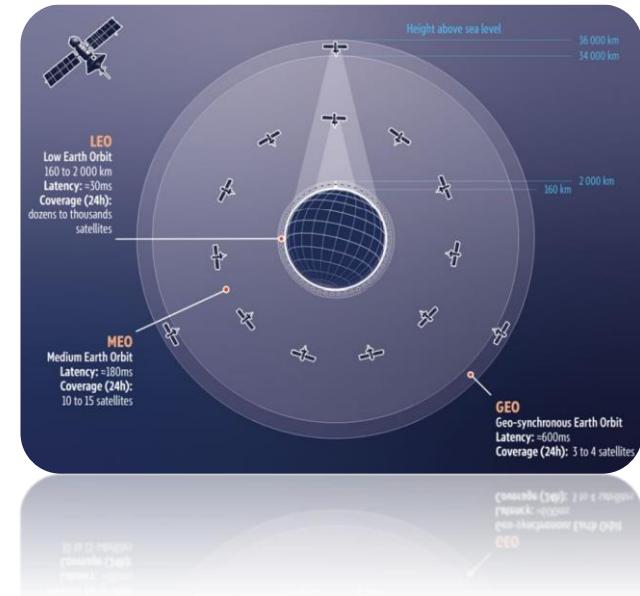
# Key takeaways (2)

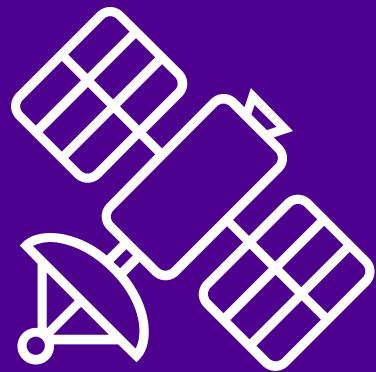
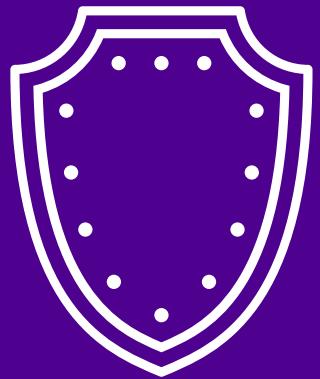
- **LEO signals and satellite constellations** specifically dedicated to PNT are transitioning towards practical implementation
- Receiver specific implementation that is yet to be emerged as a commercial solution to exploit **GNSS+INS+LEO+SOOP** with intelligent fallback mechanism
- **Space-borne interference monitoring at LEO** can be a very cost-effective solution with a global coverage, including monitoring of interference over sea and difficult terrain with limited physical access
- Another important expected technological evolution is the **coupling of communication and localization capabilities**, which is expected to benefit all sectors, including surveillance and communication applications



# Key takeaways (3)

- There is currently **little coordinated effort** on a European level to **fight** a potentially pan-European GNSS **interference problem** (i.e., military-level jamming, wide-spread jamming that can cause serious threat to safety of life applications, etc.)
- A **wide area GNSS threat monitoring system** can be developed utilizing existing national or international continuously operated reference stations, that can simultaneously monitor all GNSS frequency bands
- **Crowdsourced interference detection** is a relatively new concept, and researcher are looking at how crowdsourced GNSS data could be better utilized for GNSS interference/signal quality heatmap generation.
  - This heatmap data can then be utilized for different perspectives including real time optimum route guidance alerting to affected GNSS stakeholders of severe GNSS outage





# Thank you!

Any questions or comments?

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